

## Practice Problem Sets

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- The practice problem sets are practices for AS.110.653 Stochastic Differential Equations instructed by *Dr. Xiong Wang* at *Johns Hopkins University* in the Spring 2025 semester.
  - Dr. Wang has really dedicated a lot into designing and executing the class. We greatly appreciate his instructions throughout the course and his assistance in tackling on these problems.
- Exercises numbers refer to the course textbook [Øksendal]:
  - *Stochastic Differential Equations: An Introduction with Applications* by Bernt Øksendal.
- The solutions might contain minor typos or errors. Please point out any notable error(s) through [this link](#).

## I Problem Set 1

**Problem I.1.** (Exercise 2.1 on [Øksendal]). Suppose that  $X : \Omega \rightarrow \mathbb{R}$  is a function which assumes only countably many values  $a_1, a_2, \dots \in \mathbb{R}$ .

(a) Show that  $X$  is a random variable if and only if:

$$X^{-1}(a_k) \in \mathcal{F} \text{ for all } k = 1, 2, \dots. \quad (1)$$

*Proof.* Here, note that  $X$  assumes only countably many values  $a_1, a_2, \dots \in \mathbb{R}$ , and denote the set of these points as  $X(\Omega)$ , for any open set  $U \subset \mathbb{R}$ , its preimage  $X^{-1}(U)$  must be a subset of  $X(\Omega)$ , i.e.,  $X^{-1}(U) \subset X^{-1}(X(\Omega))$ . Now, let  $I \subset \mathbb{N}^+$  be a indexed set in which  $a_i \in U$ , then the preimage of  $U$  is simply the countable union  $X^{-1}(U) = \bigcup_{i \in I} X^{-1}(a_i)$ .

Recall that for a  $\sigma$ -algebra, if a sequence of set is in it, its countable union must be still in it. Note that  $X(\Omega)$  is countable, it is discrete (or not containing an interval in  $\mathbb{R}$ , which making it uncountable), so for any  $a_j$  where  $j \in \mathbb{N}^+$ , there exists some  $\epsilon > 0$  such that  $a_k \notin N_\epsilon(a_j)$  for all  $k \neq j$ . By such, we know that  $X$  being a random variable is equivalent to saying that  $X^{-1}(U) \in \mathcal{F}$  for all open set  $U \subset \mathbb{R}$ , which is equivalent to saying that  $X^{-1}(\bigcup_{i \in I} a_i) \in \mathcal{F}$  for all possible  $I \in \mathcal{P}(\mathbb{N}^+)$ , which is equivalently to  $X^{-1}(a_k) \in \mathcal{F}$  for all  $k \in \mathbb{Z}^+$ , as desired.  $\square$

(b) Suppose (1) holds, show that:

$$\mathbb{E}[|X|] = \sum_{k=1}^{\infty} |a_k| \mathbb{P}[X = a_k]$$

*Proof.* Now, as we shall evaluate the expectation, while  $X(\Omega)$  is countable, we have:

$$\begin{aligned} \mathbb{E}[|X|] &= \int_{\Omega} |X(\omega)| d\mathbb{P}(\omega) = \int_{X(\Omega)} |a| d\mathbb{P}(X^{-1}(a)) \\ &= \sum_{a \in X(\Omega)} |a| \mathbb{P}(X^{-1}(a)) = \sum_{k=1}^{\infty} |a_k| \mathbb{P}[X = a_k], \end{aligned}$$

as desired.  $\square$

(c) If (1) holds and  $\mathbb{E}[|X|] < \infty$ , show that:

$$\mathbb{E}[X] = \sum_{k=1}^{\infty} a_k \mathbb{P}[X = a_k].$$

*Proof.* By (1) and  $\mathbb{E}[|X|] < \infty$ , we know that  $|X(\omega)|$  is integrable, then, we may evaluate the integral without the absolute value sign (which is not necessarily positive):

$$\begin{aligned} \mathbb{E}[X] &= \int_{\Omega} X(\omega) d\mathbb{P}(\omega) = \int_{X(\Omega)} a d\mathbb{P}(X^{-1}(a)) \\ &= \sum_{a \in X(\Omega)} a \mathbb{P}(X^{-1}(a)) = \sum_{k=1}^{\infty} a_k \mathbb{P}[X = a_k]. \end{aligned}$$

Note that based on the definition of Lebesgue integration, a function is integrated on the positive and negative parts, respectively, so we must enforce convergence in absolute value (absolute convergence) for the integral to be well defined.  $\square$

(d) If (1) holds and  $f : \mathbb{R} \rightarrow \mathbb{R}$  is measurable and bounded, show that:

$$\mathbb{E}[f(X)] = \sum_{k=1}^{\infty} f(a_k) \mathbb{P}[X = a_k].$$

*Proof.* First, we need to show that  $\mathbb{E}[|f(X)|]$  is finite. Since  $f$  is bounded, there exists some  $C \in \mathbb{R}^+$  such that  $|f(x)| < C$  for all  $x \in \mathbb{R}$ . Moreover, since  $f$  is measurable, and  $X(\Omega)$  is discrete, then  $f(X(\Omega))$  is discrete (thus measurable) and for any  $x \in f(X(\Omega))$ ,  $f^{-1}(x)$  is measurable, hence, we have the expectation as:

$$\begin{aligned} \mathbb{E}[|f(X)|] &= \int_{\Omega} |f(X(\omega))| d\mathbb{P}(\omega) = \int_{X(\Omega)} |f(a)| d\mathbb{P}(X^{-1}(a)) \\ &= \sum_{a \in X(\Omega)} |f(a)| \mathbb{P}(X^{-1}(a)) = \sum_{k=1}^{\infty} |a_k| \mathbb{P}[X = a_k] \\ &< C \sum_{k=1}^{\infty} \mathbb{P}[X = a_k] = C < \infty. \end{aligned}$$

Hence, it is integrable, so we may find the expectation without absolute value sign, that is:

$$\begin{aligned} \mathbb{E}[f(X)] &= \int_{\Omega} f(X(\omega)) d\mathbb{P}(\omega) = \int_{X(\Omega)} f(a) d\mathbb{P}(X^{-1}(a)) \\ &= \sum_{a \in X(\Omega)} f(a) \mathbb{P}(X^{-1}(a)) = \sum_{k=1}^{\infty} f(a_k) \mathbb{P}[X = a_k], \end{aligned}$$

which finishes the proof.  $\square$

**Problem I.2.** (Exercise 2.3 on [Øksendal]). Let  $\{\mathcal{H}_i\}_{i \in I}$  be a family of  $\sigma$ -algebras on  $\Omega$ . Prove that:

$$\mathcal{H} = \bigcap \{\mathcal{H}_i : i \in I\}$$

is again a  $\sigma$ -algebra.

*Proof.* First, we note that each  $\sigma$ -algebra contains  $\emptyset$ , hence their intersection shall still contain  $\emptyset$ .

Now, for any  $F \in \mathcal{H}$ , we know that  $F \in \mathcal{H}_i$  for all  $i \in I$ , then  $F^c \in \mathcal{H}_i$  for all  $i \in I$ , thus  $F^c \in \mathcal{H}$ .

Eventually, let  $\{F_a\}_{a \in \mathbb{N}^+} \subset \mathcal{H}$  be an arbitrary sequence, then  $\{F_a\}_{a \in \mathbb{N}^+} \subset \mathcal{H}_i$  for all  $i \in I$ , then  $\bigcup_{a \in \mathbb{N}^+} F_a \in \mathcal{H}_i$  for all  $i \in I$ , hence the countable union is in  $\mathcal{H}$ .

Thus,  $\mathcal{H}$  is a  $\sigma$ -algebra.  $\square$

**Problem I.3.** (Exercise 2.4 in [Øksendal]).

(a) Let  $X : \Omega \rightarrow \mathbb{R}^n$  be a random variable such that:

$$\mathbb{E}[|X|^p] < \infty \text{ for some } p, 0 < p < \infty.$$

Prove *Chebychev's inequality*:

$$\mathbb{P}[|X| \geq \lambda] \leq \frac{1}{\lambda^p} \mathbb{E}[|X|^p] \text{ for all } \lambda > 0.$$

*Hint:*  $\int_{\Omega} |X|^p d\mathbb{P} \geq \int_A |X|^p d\mathbb{P}$ , where  $A = \{\omega : |X| \geq \lambda\}$ .

*Proof.* Here, we first note that  $A \subset \Omega$ , so we trivially have:

$$\int_{\Omega} |X|^p d\mathbb{P} \geq \int_A |X|^p d\mathbb{P},$$

by the monotonicity measure of subsets.

Then, we may build an inequality as:

$$\begin{aligned} \int_{\Omega} |X|^p d\mathbb{P} &\geq \int_A |X|^p d\mathbb{P} = \int_A |X(\omega)|^p d\mathbb{P}(\omega) \\ &\geq \int_A \lambda^p d\mathbb{P}(\omega) = \lambda^p \int_A d\mathbb{P}(\omega) = \lambda^p \mathbb{P}(A) = \lambda^p \mathbb{P}[|X| \geq \lambda]. \end{aligned}$$

Then, by dividing both sides with  $\lambda^p$ , we now have:

$$\mathbb{P}[|X| \geq \lambda] \leq \frac{1}{\lambda^p} \int_{\Omega} |X|^p d\mathbb{P} = \frac{1}{\lambda^p} \mathbb{E}[|X|^p],$$

which completes the proof.  $\square$

(b) Suppose there exists  $k > 0$  such that:

$$M = \mathbb{E}[\exp(k|X|)] < \infty.$$

Prove that  $\mathbb{P}[|X| \geq \lambda] \leq M e^{-k\lambda}$  for all  $\lambda \geq 0$ .

*Proof.* Here, can first note that since  $\exp(-)$  is monotonic, so:

$$\mathbb{P}[|X| \geq \lambda] = \mathbb{P}[|\exp(k|X|)| \geq e^{k\lambda}].$$

Since we assume that  $M = \mathbb{E}[\exp(k|X|)] < \infty$ , we can apply part (a) with  $p = 1$  as:

$$\mathbb{P}[|\exp(k|X|)| \geq e^{k\lambda}] \leq \frac{1}{e^{k\lambda}} \mathbb{E}[|\exp(k|X|)|] = \frac{1}{e^{k\lambda}} \mathbb{E}[\exp(k|X|)] = M e^{-k\lambda},$$

and it combines with the previous equality as:

$$\mathbb{P}[|X| \geq \lambda] \leq M e^{-k\lambda},$$

as desired.  $\square$

**Problem I.4.** (Exercise 2.6 in [Øksendal]). Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space and let  $A_1, A_2, \dots$  be sets in  $\mathcal{F}$  such that:

$$\sum_{k=1}^{\infty} \mathbb{P}(A_k) < \infty.$$

Prove the *Borel-Cantelli* lemma:

$$\mathbb{P}\left(\bigcap_{m=1}^{\infty} \bigcup_{k=m}^{\infty} A_k\right) = 0,$$

i.e., the probability that  $\omega$  belongs to infinitely many  $A_k$ 's is zero.

*Proof.* First, we note that  $\bigcap_{m=1}^{\infty} \bigcup_{k=m}^{\infty} A_k$  is a countable intersection of countable union of measurable set, hence  $\bigcap_{m=1}^{\infty} \bigcup_{k=m}^{\infty} A_k \in \mathcal{F}$ , i.e. it is measurable.

Then, note that the infinite sum  $\sum_{k=1}^{\infty} \mathbb{P}(A_k) < \infty$ , then for any  $\epsilon > 0$ , there exists some  $m > 0$  such that:

$$\sum_{k=m}^{\infty} \mathbb{P}(A_k) < \epsilon.$$

Thus, we can note that by the fact that an intersection is a subset and by the countable additivity of measure, we have:

$$\mathbb{P}\left(\bigcap_{m=1}^{\infty} \bigcup_{k=m}^{\infty} A_k\right) \leq \mathbb{P}\left(\bigcup_{k=m}^{\infty} A_k\right) < \epsilon.$$

Now, since  $\mathbb{P}(\bigcap_{m=1}^{\infty} \bigcup_{k=m}^{\infty} A_k) < \epsilon$  for all  $\epsilon > 0$ , we have:

$$\mathbb{P}\left(\bigcap_{m=1}^{\infty} \bigcup_{k=m}^{\infty} A_k\right) = 0,$$

which completes the proof of the *Borel-Cantelli* lemma. □

**Problem I.5.** Prove Lebesgue's dominance convergence theorem under assumption "convergence in probability." You can apply the version under assumption "convergence almost surely."

Here, we first recall Lebesgue's dominance convergence theorem:

**Theorem.** Suppose  $\{f_n\}_{n=1}^{\infty}$  is a sequence of measurable functions such that  $f_n(x) \rightarrow f(x)$  for a.e.  $x$ , as  $n \rightarrow \infty$ . If  $|f_n(x)| \leq g(x)$ , where  $g$  is integrable, then:

$$\int |f_n - f| \rightarrow 0 \text{ as } n \rightarrow \infty,$$

and consequently:

$$\int f_n \rightarrow \int f \text{ as } n \rightarrow \infty.$$

To consider this under the "convergence in probability," the theorem becomes:

**Theorem.** Suppose  $\{X_n\}_{n=1}^\infty$  is a sequence of random variables  $X_i : \Omega \rightarrow \mathbb{R}$  such that  $X_n \xrightarrow{\mathbb{P}} X$ , where  $X : \Omega \rightarrow \mathbb{R}$  is a random variable, as  $n \rightarrow \infty$ . If  $|X_n| \leq Y$ , for random variable  $Y : \Omega \rightarrow \mathbb{R}$ , where  $\mathbb{E}[|Y|] < \infty$ , then:

$$\mathbb{E}[|X_n - X|] \rightarrow 0 \text{ as } n \rightarrow \infty,$$

and consequently:

$$\mathbb{E}[X_n] \rightarrow \mathbb{E}[X] \text{ as } n \rightarrow \infty.$$

*Proof.* Let  $\epsilon > 0$  be arbitrary, we define:

$$\Omega_\epsilon := \{\omega \in \Omega : |X_n(\omega) - X(\omega)| \leq \epsilon\},$$

and correspondingly:

$$\Omega_\epsilon^c := \{\omega \in \Omega : |X_n(\omega) - X(\omega)| > \epsilon\}.$$

By the definition of convergence in probability, there exists some  $n \in \mathbb{N}^+$  such that  $\mathbb{P}[|X_n - X| > \epsilon] < \epsilon$ , so we have  $\mathbb{P}(\Omega_\epsilon^c) < \epsilon$  with arbitrarily large  $n$ .

Also, since  $\mathbb{E}[|Y|] < \infty$ , we note that  $|Y|$  must be bounded a.e., that is  $|Y| < k$  for some  $k \in \mathbb{R}^+$  a.e.

Then, we want to decompose our expectation as:

$$\begin{aligned} \mathbb{E}[|X_n - X|] &= \int_{\Omega} |X_n(\omega) - X(\omega)| d\mathbb{P}(\omega) \\ &= \int_{\Omega_\epsilon} |X_n(\omega) - X(\omega)| d\mathbb{P}(\omega) + \int_{\Omega_\epsilon^c} |X_n(\omega) - X(\omega)| d\mathbb{P}(\omega) \\ &\leq \mathbb{P}(\Omega_\epsilon)\epsilon + \int_{\Omega_\epsilon^c} 2|Y(\omega)| d\mathbb{P}(\omega) \\ &\leq 1 \cdot \epsilon + 2k\epsilon \leq (2k+1)\epsilon. \end{aligned}$$

Thus, as  $n \rightarrow \infty$ ,  $\mathbb{E}[|X_n - X|] < (2k+1)\epsilon$  for all  $\epsilon > 0$ , so  $\mathbb{E}[|X_n - X|] \rightarrow 0$ .

Afterwards, we shall note that:

$$|\mathbb{E}[X_n] - \mathbb{E}[X]| = |\mathbb{E}[X_n - X]| \leq \mathbb{E}[|X_n - X|] \rightarrow 0 \text{ as } n \rightarrow \infty,$$

so we have  $\mathbb{E}[X_n] \rightarrow \mathbb{E}[X]$  as  $n \rightarrow \infty$ . □

## II Problem Set 2

**Problem II.1.** (Exercise 2.17 on [Øksendal]). If  $X_t(\cdot) : \Omega \rightarrow \mathbb{R}$  is a continuous stochastic process, then for  $p > 0$  the  $p$ -th variation process of  $X_t$ ,  $\langle X, X \rangle_t^{(p)}$  is defined by:

$$\langle X, X \rangle_t^{(p)}(\omega) = \lim_{\Delta t_k \rightarrow 0} \sum_{t_k \leq t} |X_{t_{k+1}}(\omega) - X_{t_k}(\omega)|^p$$

as the limit in probability where  $0 = t_1 < t_2 < \dots < t_n = t$  and  $\Delta t_k = t_{k+1} - t_k$ . In particular, if  $p = 1$ , this process is called the *total variation process* and if  $p = 2$ , it is called the *quadratic variation process*. For Brownian motion  $B_t \in \mathbb{R}$ , we now show that the quadratic variation process is simply:

$$\langle B, B \rangle_t(\omega) = \langle B, B \rangle_t^{(2)}(\omega) = t \text{ a.s.}$$

(a) Define:

$$\Delta B_k = B_{t_{k+1}} - B_{t_k},$$

and put:

$$Y(t, \omega) = \sum_{t_k \leq t} (\Delta B_k(\omega))^2.$$

Show that:

$$\mathbb{E} \left[ \left( \sum_{t_k \leq t} (\Delta B_k)^2 - t \right)^2 \right] = 2 \sum_{t_k \leq t} (\Delta t_k)^2,$$

and deduce that  $Y(t, \cdot) \rightarrow t$  in  $L^2(P)$  as  $\Delta t_k \rightarrow 0$ .

*Proof.* Here, we first recall the property of Brownian motion so that:

$$\Delta B_k \sim \mathcal{N}(0, t_{k+1} - t_k) = \mathcal{N}(0, \Delta t_k).$$

Here, we note that the Brownian motions are independent, so we have:

$$\begin{aligned} \mathbb{E} \left[ \left( \sum_{t_k \leq t} (\Delta B_k)^2 - t \right)^2 \right] &= \mathbb{E} \left[ \sum_{t_k \leq t} ((\Delta B_k)^2 - t)^2 \right] = \sum_{t_k \leq t} \mathbb{E} [((\Delta B_k)^2 - t)^2] \\ &= \sum_{t_k \leq t} \mathbb{E} [(\Delta B_k)^4 - 2t(\Delta B_k)^2 + t^2]. \end{aligned}$$

Recall the fourth moment being  $3\sigma^4 = 3(\Delta t_k)^2$ , the second moment as  $\sigma^2 = \Delta t_k$ , so we have the expectation as:

$$\mathbb{E} \left[ \left( \sum_{t_k \leq t} (\Delta B_k)^2 - t \right)^2 \right] = 3(\Delta t_k)^2 - 2(\Delta t_k)^2 + (\Delta t_k)^2 = 2(\Delta t_k)^2.$$

Hence, as we consider the expectation as integral, we have:

$$\int_{\Omega} \left( \sum_{t_k \leq t} (\Delta B_k(\omega))^2 - t \right)^2 d\mathbb{P}(\omega) \rightarrow 0 \text{ as } \Delta t_k \rightarrow 0,$$

so we have  $L^2$  convergence that  $Y(t, \cdot) := \sum_{t_k \leq t} (\Delta B_k(\omega))^2 \rightarrow t$ , as required.  $\square$

(b) Use (a) to prove that a.a. paths of Brownian motion do not have a bounded variation on  $[0, t]$ , i.e. the total variation of Brownian motion is infinite, a.s.

*Proof.* First, we may obtain the inequality that:

$$\sum_{t_k \leq t} |\Delta B_k(\omega)| = \sum_{t_k \leq t} \frac{|\Delta B_k(\omega)|^2}{|\Delta B_k(\omega)|} \geq \frac{1}{\sup_{t_k \leq t} |\Delta B_k(\omega)|} \sum_{t_k \leq t} |\Delta B_k(\omega)|^2.$$

Again, note that we want  $\Delta t_k \rightarrow 0$ , then we have  $|\Delta B_k(\omega)| \rightarrow 0$  for all  $t_k \leq t$ , thus:

$$\begin{aligned} \langle B, B \rangle_t^{(1)}(\omega) &= \lim_{\Delta t_k \rightarrow 0} \sum_{t_k \leq t} |\Delta B_k(\omega)| \geq \lim_{\Delta t_k \rightarrow 0} \frac{1}{\sup_{t_k \leq t} |\Delta B_k(\omega)|} \sum_{t_k \leq t} |\Delta B_k(\omega)|^2 \\ &= \langle B, B \rangle_t^{(2)}(\omega) \lim_{\Delta t_k \rightarrow 0} \frac{1}{\sup_{t_k \leq t} |\Delta B_k(\omega)|} = t \lim_{\Delta t_k \rightarrow 0} \frac{1}{\sup_{t_k \leq t} |\Delta B_k(\omega)|} = +\infty. \end{aligned}$$

Hence, we have the total variation of the Brownian motion being infinite almost surely.  $\square$

**Problem II.2.** (Exercise 2.18 on [Øksendal]).

(a) Let  $\Omega = \{1, 2, 3, 4, 5\}$  and let  $\mathcal{U}$  be the collection:

$$\mathcal{U} = \{\{1, 2, 3\}, \{3, 4, 5\}\}$$

of subsets of  $\Omega$ . Find the smallest  $\sigma$ -algebra containing  $\mathcal{U}$ , i.e., the  $\sigma$ -algebra  $\mathcal{H}_{\mathcal{U}}$  generated by  $\mathcal{U}$ .

**Solution.** From the beginning, the  $\sigma$ -algebra must contain the empty set and its compliment,  $\{\emptyset, \Omega\}$ . Then, consider the sets in the collection and their (countable union), we have:

$$\{\emptyset, \{1, 2, 3\}, \{3, 4, 5\}, \{1, 2, 3, 4, 5\} = \Omega\}.$$

Then, consider the complimentary sets, we must have:

$$\{\emptyset, \{1, 2, 3\}, \{3, 4, 5\}, \Omega, \{4, 5\}, \{1, 2\}\},$$

while this would have created another union and a compliment, so we have:

$$\{\emptyset, \{3\}, \{1, 2\}, \{4, 5\}, \{1, 2, 3\}, \{3, 4, 5\}, \{1, 2, 4, 5\}, \Omega\}.$$

Now, one can verify that the above collection contains  $\mathcal{U}$ , has the empty set, compliments, and countable unions, so the  $\sigma$ -algebra is:

$$\mathcal{H}_{\mathcal{U}} = \boxed{\{\emptyset, \{3\}, \{1, 2\}, \{4, 5\}, \{1, 2, 3\}, \{3, 4, 5\}, \{1, 2, 4, 5\}, \Omega\}}.$$

$\square$

(b) Define  $X : \Omega \rightarrow \mathbb{R}$  by:

$$X(1) = X(2) = 0, \quad X(3) = 10, \quad X(4) = X(5) = 1.$$

Is  $X$  measurable with respect  $\mathcal{H}_{\mathcal{U}}$ ?

**Solution.** Yes. By [Problem I.1\(a\)](#), since we have a (at most) countable image, we can check the preimage of each single value of output. Note that:

$$X^{-1}(0) = \{1, 2\} \in \mathcal{H}_{\mathcal{U}}, \quad X^{-1}(10) = \{3\} \in \mathcal{H}_{\mathcal{U}}, \quad \text{and } X^{-1}(1) = \{4, 5\} \in \mathcal{H}_{\mathcal{U}},$$

so  $X$  is  $\mathcal{H}_{\mathcal{U}}$ -measurable. □

(c) Define  $Y : \Omega \rightarrow \mathbb{R}$  by:

$$Y(1) = 0, \quad Y(2) = Y(3) = Y(4) = Y(5) = 1.$$

Find the  $\sigma$ -algebra  $\mathcal{H}_Y$  generated by  $Y$ .

**Solution.** Here, we may note that the preimage is discrete, so we consider the collection:

$$\mathcal{Y} = \{\{1\}, \{2, 3, 4, 5\}\},$$

and our solution is the  $\sigma$ -algebra generated by  $\mathcal{Y}$ , namely:

$$\mathcal{H}_Y = \boxed{\{\emptyset, \{1\}, \{2, 3, 4, 5\}, \Omega\}}.$$
□

**Problem II.3.** Suppose  $\{Z_k\}_{k=1}^{\infty}$  are independent  $\mathcal{N}(0, 1)$  random variables. Show that  $|Z_n(\omega)| = \mathcal{O}(\sqrt{\log(n)})$  as  $n \rightarrow \infty$  almost surely.

*Hint:* You may need Borel-Cantelli lemma.

*Proof.* Here, we construct our set of events  $\{A_k\}_{k=1}^{\infty}$ . We let:

$$A_k := \{\omega \in \Omega : |Z_k| > 2\sqrt{\log k}\}.$$

Then, we note that:

$$\mathbb{P}(A_k) = 2\mathbb{P}(Z_k > 2\sqrt{\log k}) = 1 - \text{erf}(\sqrt{2\log k}),$$

and we want to show that  $\sum_{k=1}^{\infty} \mathbb{P}(A_k) < +\infty$ .

Here, we first notice that  $\mathbb{P}(A_2) \lesssim 0.095891 \ll 0.25 = 1/2^2$ , and we take their derivatives as:

$$\begin{aligned} \frac{d}{dk} [1 - \text{erf}(\sqrt{2\log k})] &= -\frac{2}{\sqrt{\pi}} \frac{d}{dk} \int_0^{\sqrt{2\log k}} e^{-t^2} dt \\ &= -\frac{2}{\sqrt{\pi}} \exp(-2\log k) \cdot \frac{1}{k\sqrt{2\log k}} = -\frac{2/\sqrt{\pi}}{k^3 \sqrt{\log k}}. \end{aligned}$$

Note that when we take the derivative of  $1/k^2$  with respect to  $k$ , we obtain  $-2/k^3$ , in which we have:

$$\frac{d}{dk} \left[ \frac{1}{k^2} \right] = -\frac{2}{k^3} > -\frac{2/\sqrt{\pi}}{k^3 \sqrt{\log k}} = \frac{d}{dk} [1 - \text{erf}(\sqrt{2 \log k})] \text{ for } k > 0.$$

Hence, we may conclude that:

$$\mathbb{P}(A_k) < \frac{1}{k^2} \text{ for all } k \geq 2.$$

Hence, we have:

$$\sum_{k=1}^{\infty} \mathbb{P}(A_k) \leq 1 + \sum_{k=2}^{\infty} \mathbb{P}(A_k) \leq 1 + \sum_{k=1}^{\infty} \frac{1}{k^2} < +\infty,$$

by the convergence of harmonic series, so our sets  $A_k$  satisfies the condition Borel-Cantelli lemma.

Now, since  $\{Z_k\}_{k=1}^{\infty}$  is independent, we have:

$$\mathbb{P} \left( \limsup_{k \rightarrow \infty} (A_k) \right) = \mathbb{P} \left( \bigcap_{m=1}^{\infty} \bigcup_{k=m}^{\infty} A_k \right) = 0,$$

which means that:

$$\mathbb{P}(\{\omega \in \Omega : |Z_k(\omega)| > 2\sqrt{\log k}\}) \rightarrow 0 \text{ as } k \rightarrow \infty,$$

which implies that  $|Z_k(\omega)| \leq 2\sqrt{\log k}$  for all  $\omega \in \Omega \setminus N$  where  $N$  is a null set, and hence:

$$|Z_n(\omega)| \leq 2\sqrt{\log n} \text{ as } n \rightarrow \infty \text{ a.s.},$$

which completes the proof. □

**Problem II.4.** Let  $\{B_t\}_{t \geq 0}$  be one-dimensional Brownian motion.

(a) Find the density of the random vector  $(B_s, B_t)$  where  $0 < s < t < \infty$ .

**Solution.** Here, for the density function, we are able to express the probability as:

$$\begin{aligned} \mathbb{P}(B_s \in F_1, B_t \in F_2) &= \int_{F_1 \times F_2} \rho(s, x) \rho(t-s, y-x) dx dy \\ &= \int_{F_1 \times F_2} \frac{1}{\sqrt{2\pi s}} \exp \left( -\frac{|x|^2}{2s} \right) \cdot \frac{1}{\sqrt{2\pi(t-s)}} \exp \left( -\frac{|y-x|^2}{2(t-s)} \right) dx dy \\ &= \int_{F_1 \times F_2} \frac{1}{2\pi\sqrt{s(t-s)}} \exp \left( -\frac{|x|^2}{2s} - \frac{|y-x|^2}{2(t-s)} \right) dx dy. \end{aligned}$$

Hence, the density function is:

$$\rho(s, t, x, y) = \boxed{\frac{1}{2\pi\sqrt{s(t-s)}} \exp \left( -\frac{|x|^2}{2s} - \frac{|y-x|^2}{2(t-s)} \right)}.$$

□

(b) Find the conditional density of the vector  $(B_s, B_t)$  where  $0 < s < t < 1$  under the condition  $B_1 = 0$ .

**Solution.** Here, we consider the conditional probability as:

$$\mathbb{P}(B_s \in F_1, B_t \in F_2 \mid B_1 = 0) = \frac{\mathbb{P}(B_s \in F_1, B_t \in F_2, B_1 = 0)}{\mathbb{P}(B_1 = 0)}.$$

Hence, the density function will be given as:

$$\begin{aligned} \rho(s, t, x, y) &= \frac{\rho(s, x)\rho(t-s, y-x)\rho(1-t, 0-y)}{\rho(1, 0)} \\ &= \frac{\frac{1}{\sqrt{2\pi s}} \exp\left(-\frac{|x|^2}{2s}\right) \cdot \frac{1}{\sqrt{2\pi(t-s)}} \exp\left(-\frac{|y-s|^2}{2(t-s)}\right) \cdot \frac{1}{\sqrt{2\pi(1-t)}} \exp\left(-\frac{|y|^2}{2(1-t)}\right)}{\frac{1}{\sqrt{2\pi}} \exp\left(-\frac{|0|^2}{2}\right)} \\ &= \boxed{\frac{1}{2\pi\sqrt{s(t-s)(1-t)}} \exp\left(-\frac{|x|^2}{2s} - \frac{|y-s|^2}{2(t-s)} - \frac{|y|^2}{2(1-t)}\right)}. \end{aligned}$$

(c) Consider the process  $X_t = e^{-\alpha t/2} B_{e^{\alpha t}}$ . Find the probability density of  $(X_{t_1}, \dots, X_{t_n})$ .

**Solution.** Again, the vector of the Brownian motion is the random vector of a multi-normal distribution, that is:

$$(B_{e^{\alpha t_1}}, B_{e^{\alpha t_2}}, \dots, B_{e^{\alpha t_n}}) \sim \mathcal{N}((0, 0, \dots, 0), \Sigma),$$

where  $\Sigma \in \mathbb{R}^{n \times n}$  is a positive definite variance matrix, now we consider the exponentials, so the distribution would be:

$$(X_{t_1}, \dots, X_{t_n}) \sim \mathcal{N}((0, 0, \dots, 0), \Sigma),$$

hence, so the density function is:

$$\rho_{(X_{t_1}, \dots, X_{t_n}) \sim \mathcal{N}((0, 0, \dots, 0)}(x_1, x_2, \dots, x_n) = \boxed{2\pi|\Sigma|^{-1/2} \exp\left(-\frac{1}{2}(x_1, \dots, x_n)^\top \Sigma (x_1, \dots, x_n)\right)}.$$

**Problem II.5.** Let  $\{X_n\}_{n \geq 1}$  be a sequence of independent random variables on the probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  with mean 0 and variance  $\sigma^2$ . Denote  $\mathcal{F}_n = \sigma\{X_k, 1 \leq k \leq n\}$ . Let  $\{Z_n\}_{n \geq 1}$  be a square-integrable process *predictable* with respect to  $\mathcal{F}_n$  (i.e.,  $Z_{n+1}$  is  $\mathcal{F}_n$ -measurable).

(a) Show that  $Y_n = \sum_{k=1}^n Z_k X_k$  is a square integrable martingale.

*Proof.* First, we want to show that  $Y_n$  is square integrable, for each finite  $n$ , it is a finite sum of random

variables, so we can reduce to the case of showing that  $Z_k X_k$  is square integrable. Consider that:

$$\begin{aligned} \int_{\Omega} |Z_k(\omega) X_k(\omega)|^2 d\omega &= \int_{\{\omega \in \Omega: |\omega| \leq \delta\}} |Z_k(\omega) X_k(\omega)|^2 d\omega + \int_{\{\omega \in \Omega: |\omega| > \delta\}} |Z_k(\omega) X_k(\omega)|^2 d\omega \\ &\leq C_1 \int_{\{\omega \in \Omega: |\omega| \leq \delta\}} |Z_k(\omega)|^2 d\omega + C_2 \int_{\{\omega \in \Omega: |\omega| > \delta\}} |X_k(\omega)|^2 d\omega. \end{aligned}$$

Note that with choice of  $\delta$ ,  $Z_k$  will become bounded for larger than  $\delta$  as it is square integrable, and  $X_k$  will be bounded for smaller than  $\delta$  as it has mean of 0, hence the function is still square integrable.

For the martingale part, for any  $n \geq 1$  and  $j > n$ , we have the conditional expectation as:

$$\mathbb{E}[Y_j \mid Y_1, \dots, Y_k] = \sum_{i=1}^j \mathbb{E}[Z_i X_i \mid Y_1, \dots, Y_k] = \sum_{i=1}^k Z_i X_i + \sum_{i=k+1}^j \underbrace{Z_i \mathbb{E}[X_i]}_{=0} = Y_k,$$

hence we have shown that  $Y_n$  is martingale.

Therefore,  $\{Y_n\}$  is a sequence of square integrable martingale.  $\square$

(b) Show that  $\mathbb{E}[Y_n] = 0$  and that  $\mathbb{E}[Y_n^2] = \sigma^2 \sum_{k=1}^n \mathbb{E}[Z_k^2]$ .

*Proof.* Here, we may consider the expectation based on the different measure of  $X$ :

$$\mathbb{E}[Y_n] = \sum_{k=1}^n \mathbb{E}[Z_k X_k] = \sum_{k=1}^n \int_{\mathcal{F}_n} Z_k X_k d\mathbb{P} = \sum_{k=1}^n \left( \int_{\mathcal{F}_n} Z_k d\mathbb{P} \cdot \int_{\mathcal{F}_n} X_k d\mathbb{P} \right) = 0.$$

Then, we consider the second moment as (by independence):

$$\mathbb{E}[Y_n^2] = \text{Var}[Y_n] = \sum_{k=1}^n \text{Var}[Z_k] \text{Var}[X_k] = \sum_{k=1}^n \sigma^2 \mathbb{E}[Z_k^2] = \sigma^2 \sum_{k=1}^n \mathbb{E}[Z_k^2],$$

which finishes the proof.  $\square$

(c) Let us assume  $Z_k = \frac{1}{k}$ . Is the martingale  $\{Y_n\}_{n \geq 1}$  uniformly integrable?

**Solution.** Here, we may observe from (b) that we would have  $Y_n$  having expectation and variance as:

$$\mathbb{E}[Y_n] = 0 \text{ and } \mathbb{E}[Y_n^2] = \sigma^2 \sum_{k=1}^n \mathbb{E}[Z_k^2].$$

Hence, as  $n \rightarrow \infty$ , we have  $\mathbb{E}[Y_n^2] < +\infty$  converging. Therefore, when we consider:

$$\lim_{m \rightarrow \infty} \sup_{i \geq 1} \left[ \int_{|Y_i| \geq m} |Y_i| d\mathbb{P} \right],$$

where we have  $\mathbb{P}(|Y_i| \geq m) \rightarrow 0$  as  $m \rightarrow \infty$ , and so the limit is zero and the martingale is uniformly integrable.  $\square$

### III Problem Set 3

**Problem III.1.** (Exercise 3.1 on [Øksendal]). Prove directly from the definition of Itô integrals that:

$$\int_0^t s dB_s = t B_t - \int_0^t B_s ds.$$

*Hint:* Note that:

$$\sum_j \Delta(s_j B_j) = \sum_j s_j \Delta B_j + \sum_j B_{j+1} \Delta s_j.$$

*Proof.* Here, from the definition, we note that  $s$  is already an elementary function, so we may consider the partition such that  $\Delta t \rightarrow 0$ :

$$\int_0^t s dB_s = \sum_j s_j \Delta B_j = \sum_j \Delta(s_j B_j) - \sum_j B_{j+1} \Delta s_j = t B_t - \int_0^t B_s ds,$$

as desired.  $\square$

**Problem III.2.** (Exercise 3.5 on [Øksendal]). Prove directly that:

$$M_t = B_t^2 - t$$

is an  $\mathcal{F}_t$ -martingale.

*Proof.* First, we want to show that the process is integrable, *i.e.*, for any fixed  $t > 0$ :

$$\mathbb{E}[|M_t|] = \mathbb{E}[|B_t^2 - t|] = \mathbb{E}[|\chi^2(t) - t|] < +\infty.$$

Then, we suppose any  $s \leq t$  fixed, and recall that Brownian motions are martingale, let:

$$\begin{aligned} \mathbb{E}[M_t \mid \mathcal{F}_s] &= \mathbb{E}[B_t^2 - t \mid \mathcal{F}_s] = \mathbb{E}[B_t^2 \mid \mathcal{F}_s] - t \\ &= \mathbb{E}[(B_t - B_s)^2 + 2B_t B_s - B_s^2 \mid \mathcal{F}_s] - t \\ &= \mathbb{E}[(B_t - B_s)^2 \mid \mathcal{F}_s] + \mathbb{E}[2B_t B_s \mid \mathcal{F}_s] - \mathbb{E}[B_s^2 \mid \mathcal{F}_s] - t \\ &= (t - s) + 2B_s \mathbb{E}[B_t \mid \mathcal{F}_s] - B_s^2 - t = B_s^2 - s = M_s, \end{aligned}$$

so  $M_t$  is an  $\mathcal{F}_t$ -martingale.  $\square$

**Problem III.3.** (Exercise 3.7 on [Øksendal]). A famous result of Itô (1951) gives the following formula for  $n$  times *iterated Itô integrals*:

$$n! \int \cdots \left( \int \left( \int dB_{u_1} \right) dB_{u_2} \right) \cdots dB_{u_n} = t^{\frac{n}{2}} h_n \left( \frac{B_t}{\sqrt{t}} \right), \quad (2)$$

where  $h_n$  is the *Hermite polynomial* of degree  $n$ , defined by:

$$h_n(x) = (-1)^n e^{\frac{x^2}{2}} \frac{d^n}{dx^n} \left( e^{-\frac{x^2}{2}} \right); \quad n = 0, 1, 2, \dots$$

Thus  $h_0(x) = 1$ ,  $h_1(x) = x$ ,  $h_2(x) = x^2 - 1$ ,  $h_3(x) = x^3 - 3x$ .

(a) Verify that in each of these  $n$  Itô integrals, the integrand satisfies the requirements for  $\mathcal{V}$ .

*Proof.* Here, we note that  $h_n(x)$  is integrable, and we have:

$$f_n(t, \omega) = \frac{1}{(n-1)!} t^{\frac{n-1}{2}} h_{n-1} \left( \frac{B_t}{\sqrt{t}} \right),$$

we want to show:

- $(t, \omega) \mapsto f(t, \omega)$  is  $\mathcal{B} \times \mathcal{F}$  measurable.  
Note that for  $h_n$  is measurable over  $\mathcal{B} \times \mathcal{F}$ , so it is good.
- $f(t, \omega)$  is  $\mathcal{F}_t$ -adapted, i.e.,  $\omega \mapsto f(t, \omega)$  is  $\mathcal{F}_t$ -measurable.  
Again,  $h_n$  is measurable of  $\mathcal{F}$  with fixed  $\omega$ , so it is good.
- $\mathbb{E} \left[ \int_0^T f(t, \omega)^2 dt \right] < +\infty$ .  
We have:

$$\mathbb{E} \left[ \int_0^T f(t, \omega)^2 dt \right] \leq nT^2 < +\infty.$$

Hence, the integrands satisfies the requirements of being  $\mathcal{V}$ .  $\square$

(b) Verify formula (2) for  $n = 1, 2, 3$ .

*Proof.* • ( $n = 1$ ) We have:

$$1! \int_0^t dB_{u_1} = B_t = \sqrt{t} \cdot \frac{B_t}{\sqrt{t}}.$$

• ( $n = 2$ ) We have:

$$2! \int_0^t B_{u_2} dB_{u_2} = B_t^2 - t = t \left( \frac{B_t^2}{t} - 1 \right)$$

• ( $n = 3$ ) We have:

$$\begin{aligned} 3! \int_0^t \left( \frac{1}{2} B_{u_3}^2 - \frac{1}{2} u_3 \right) dB_{u_3} &= 3 \int_0^t B_{u_3}^2 dB_{u_3} - 3 \int_0^t u_3 dB_{u_3} = B_t^3 - 3 \int_0^t B_{u_3} du_3 + 3t B_t - 3 \int_0^t B_{u_3} du_3 \\ &= B_t^3 - 3t B_t = t^{\frac{3}{2}} \left( \frac{B_t^3}{t^{\frac{3}{2}}} - 3 \frac{B_t}{\sqrt{t}} \right). \end{aligned}$$

$\square$

(c) Use (b) to prove that  $N_t = B_t^3 - 3tB_t$  is a martingale.

*Proof.* Note that Itô integrals are martingale, and since  $B_t^3 - 3tB_t$  is an Itô integral, it is martingale.  $\square$

**Problem III.4.** Compute:

(a)

$$\mathbb{E} \left[ B_s \int_0^t B_r dB_r \right].$$

**Solution.** Here, we have:

$$\mathbb{E} \left[ B_s \int_0^t B_r dB_r \right] = \mathbb{E} \left[ B_s \cdot \frac{1}{2} (B_t^2 - t) \right] = \frac{1}{2} \mathbb{E}[B_s B_t^2 - t B_s] = \frac{1}{2} \mathbb{E}[B_s B_t^2] - \frac{1}{2} t \mathbb{E}[B_s] = \frac{1}{2} \mathbb{E}[B_s B_t^2].$$

Now, we consider two distinctive cases for  $\mathbb{E}[B_s B_t^2]$ :

• ( $s \leq t$ ): We have:

$$\begin{aligned} \mathbb{E}[B_s B_t^2] &= \mathbb{E}[B_s (B_t - B_s)^2 - B_s^3 + 2B_s^2 B_t] = \mathbb{E}[B_s] \mathbb{E}[(B_t - B_s)^2] - \mathbb{E}[B_s^3] + 2\mathbb{E}[B_s^2 B_t] \\ &= 0 \cdot (t - s) - 0 + 2\mathbb{E}[B_s^2 B_t] = 2\mathbb{E}[B_s^2 B_t] \\ &= 2\mathbb{E}[B_s^2 (B_t - B_s) + B_s^3] = 2\mathbb{E}[B_s^2] \mathbb{E}[B_t - B_s] + 2\mathbb{E}[B_s^3] = 2 \cdot s \cdot 0 + 0 = 0. \end{aligned}$$

• ( $s > t$ ): Otherwise, we have:

$$\mathbb{E}[B_s B_t^2] = \mathbb{E}[B_t^2 (B_s - B_t) + B_t^3] = \mathbb{E}[B_t^2] \mathbb{E}[B_s - B_t] + \mathbb{E}[B_t^3] = t \cdot 0 + 0 = 0.$$

Hence, we have the expectation evaluated as  $\boxed{0}$ .  $\square$

(b)

$$\mathbb{E} \left[ \left( B_s \int_0^t B_r dB_r \right)^2 \right] \text{ where } s \leq t.$$

**Solution.** Here, we have:

$$\begin{aligned} \mathbb{E} \left[ \left( B_s \int_0^t B_r dB_r \right)^2 \right] &= \mathbb{E} \left[ \left( B_s \cdot \frac{1}{2} (B_t^2 - t) \right)^2 \right] = \frac{1}{4} \mathbb{E}[B_s^2 (B_t^4 - 2t^2 B_t^2 + t^2)] \\ &= \frac{1}{4} \mathbb{E}[B_s^2 B_t^4 - 2t^2 B_s^2 B_t^2 + t^2 B_s^2] = \frac{1}{4} \mathbb{E}[B_s^2 B_t^4] - \frac{1}{2} t^2 \mathbb{E}[B_s^2 B_t^2] + \frac{1}{4} t^2 \mathbb{E}[B_s^2] \\ &= \frac{1}{4} \mathbb{E}[B_s^2 B_t^4] - \frac{1}{2} t^2 \mathbb{E}[B_s^2 B_t^2] + \frac{1}{4} t^2 s. \end{aligned}$$

Now, we investigate the two respective expectations.

- For  $\mathbb{E}[B_s^2 B_t^2]$ , we have:

$$\begin{aligned}\mathbb{E}[B_s^2 B_t^2] &= \mathbb{E}[B_s^2 (B_t - B_s)^2 - B_s^4 + 2B_s^3 B_t] = \mathbb{E}[B_s^2] \mathbb{E}[(B_t - B_s)^2] - \mathbb{E}[B_s^4] + 2\mathbb{E}[B_s^3 B_t] \\ &= s(t-s) - 3s^2 + 2\mathbb{E}[B_s^3 (B_t - B_s) + B_s^4] = s(t-s) - 3s^2 + 2\mathbb{E}[B_s^3 (B_t - B_s)] + 2\mathbb{E}[B_s^4] \\ &= s(t-s) - 3s^2 + 2 \cdot 0 \cdot (t-s) + 2 \cdot 3s^2 = st + 2s^2.\end{aligned}$$

- For  $\mathbb{E}[B_s^2 B_t^4]$ , we have:

$$\begin{aligned}\mathbb{E}[B_s^2 B_t^4] &= \mathbb{E}[B_s^2 (B_t - B_s)^4 + 4B_t^3 B_s^3 - 6B_t^2 B_s^4 + 4B_t B_s^5 - B_s^6] \\ &= \mathbb{E}[B_s^2 (B_t - B_s)^4] + 4\mathbb{E}[B_t^3 B_s^3] - 6\mathbb{E}[B_t^2 B_s^4] + 4\mathbb{E}[B_t B_s^5] - \mathbb{E}[B_s^6] \\ &= s \cdot 3 \cdot (t-s)^2 + 4\mathbb{E}[B_t^3 B_s^3] - 6\mathbb{E}[B_t^2 B_s^4] + 4\mathbb{E}[B_t B_s^5] - 15s^3 \\ &= 3t^2s - 6ts^2 - 12s^3 + 4\mathbb{E}[B_t^3 B_s^3] - 6\mathbb{E}[B_t^2 B_s^4] + 4\mathbb{E}[B_t B_s^5].\end{aligned}$$

Now, we have to evaluate the next terms:

- For  $\mathbb{E}[B_t B_s^5]$ , we have:

$$\mathbb{E}[B_t B_s^5] = \mathbb{E}[B_s^5 (B_t - B_s) + B_s^6] = 15s^3.$$

- For  $\mathbb{E}[B_t^2 B_s^4]$ , we have:

$$\mathbb{E}[B_t^2 B_s^4] = \mathbb{E}[B_s^4 (B_t - B_s)^2 + 2B_s^5 B_t - B_s^6] = 3s^2 \cdot (t-s) + 30s^3 - 15s^3 = 3ts^2 + 12s^3.$$

- For  $\mathbb{E}[B_t^3 B_s^3]$ , we have:

$$\begin{aligned}\mathbb{E}[B_t^3 B_s^3] &= \mathbb{E}[B_s^3 (B_t - B_s)^3 + 3B_s^4 B_t^2 - 3B_s^5 B_t + B_s^6] \\ &= 0 + 3(3ts^2 + 12s^3) - 3(15s^3) + 15s^3 = 9ts^2 + 6s^3.\end{aligned}$$

Now, we can combine all the calculations together:

$$\begin{aligned}\mathbb{E}[B_s^2 B_t^4] &= 3t^2s - 6ts^2 - 12s^3 + 4(9ts^2 + 6s^3) - 6(3ts^2 + 12s^3) + 4(15s^3) \\ &= 3t^2s + 12ts^2.\end{aligned}$$

Hence, we may conclude that:

$$\mathbb{E} \left[ \left( B_s \int_0^t B_r dB_r \right)^2 \right] = \frac{1}{4} (3t^2s + 12ts^2) - \frac{1}{2} t^2 (st + 2s^2) + \frac{1}{4} t^2 s = \boxed{t^2 s + 3ts^2 - \frac{1}{2} st^3 + s^2 t^2}.$$

**Problem III.5.** (Exercise 3.17 on [Øksendal]). Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space and let  $X : \Omega \rightarrow \mathbb{R}$  be a random variable with  $\mathbb{E}[|X|] < \infty$ . If  $\mathcal{G} \subset \mathcal{F}$  is a *finite*  $\sigma$ -algebra, then there exists a partition  $\Omega = \bigcup_{i=1}^n G_i$  such that  $\mathcal{G}$  consists of  $\emptyset$  and unions of some (or all) of  $G_1, \dots, G_n$ .

(a) Explain why  $\mathbb{E}[X | \mathcal{G}](\omega)$  is constant on each  $G_i$ .

*Proof.* Here, we may consider  $G$  as a random variable, namely:

$$G = \sum_{i=1}^n a_i \mathbb{1}_{G_i}, \text{ where } G_i \in \mathcal{G}.$$

Then, the conditional expectation for each given  $\omega \in G_j$  is:

$$\mathbb{E}[X | \mathcal{G}](\omega) = \sum_{i=1}^n a_i \mathbb{1}_{G_i} = a_j. \quad \square$$

(b) Assume that  $\mathbb{P}[G_i] > 0$ . Show that:

$$\mathbb{E}[X | \mathcal{G}](\omega) = \frac{\int_{G_i} X d\mathbb{P}}{\mathbb{P}(G_i)} \text{ for } \omega \in G_i.$$

*Proof.* Here, we just need to verify that:

$$\int_{G_i} \mathbb{E}[X | \mathcal{G}](\omega) d\mathbb{P}(\omega) = \int_{G_i} \frac{\int_{G_i} X d\mathbb{P}}{\mathbb{P}(G_i)} d\mathbb{P} = \frac{\int_{G_i} X d\mathbb{P}}{\mathbb{P}(G_i)} \int_{G_i} d\mathbb{P} = \frac{\int_{G_i} X d\mathbb{P}}{\mathbb{P}(G_i)} \cdot \mathbb{P}(G_i) = \int_{G_i} X d\mathbb{P},$$

so it satisfies the condition for conditional expectation.  $\square$

(c) Suppose  $X$  assumes only finitely many values  $a_1, \dots, a_m$ . Then from elementary probability theory:

$$\mathbb{E}[X | G_i] = \sum_{k=1}^m a_k \mathbb{P}[X = a_k | G_i].$$

Compare with (b) and verify that:

$$\mathbb{E}[X | G_i] = \mathbb{E}[X | \mathcal{G}](\omega) \text{ for } \omega \in G_i.$$

Thus, we may regard the conditional expectation as defined as a (substantial) generalization of the conditional expectation in the elementary probability theory.

*Proof.* Here, consider  $\omega \in G_i$  being arbitrary, we have:

$$\begin{aligned} \mathbb{E}[X | \mathcal{G}](\omega) &= \frac{\int_{G_i} X d\mathbb{P}}{\mathbb{P}(G_i)} = \frac{\sum_{k=1}^m a_k \mathbb{P}(X = a_k \wedge a_k \in G_i)}{\mathbb{P}(G_i)} \\ &= \sum_{k=1}^m \frac{a_k \mathbb{P}(X = a_k \wedge a_k \in G_i)}{\mathbb{P}(G_i)} = \sum_{k=1}^m a_k \mathbb{P}(X = a_k | G_i) = \mathbb{E}[X | G_i], \end{aligned}$$

so the general definition is aligned to the elementary probability theory definition.  $\square$

**Problem III.6.** (Exercise 3.18 on [Øksendal]). Let  $B_t$  be 1-dimensional Brownian motion and let  $\sigma \in \mathbb{R}$  be constant. Prove directly from the definition that:

$$M_t := \exp \left( \sigma B_t - \frac{1}{2} \sigma^2 t \right); \quad t \geq 0$$

is a martingale.

*Hint:* If  $s > t$ , then  $\mathbb{E}[\exp(\sigma B_s - \frac{1}{2} \sigma^2 s) | \mathcal{F}_t] = \mathbb{E}[\exp(\sigma(B_s - B_t)) \times \exp(\sigma B_t - \frac{1}{2} \sigma^2 s) | \mathcal{F}_t]$ .

*Proof.* Here, by the hint, we may notice that:

$$\begin{aligned} \mathbb{E}[M_s | \mathcal{F}_t] &= \mathbb{E} \left[ \exp \left( \sigma B_s - \frac{1}{2} \sigma^2 s \right) | \mathcal{F}_t \right] \\ &= \mathbb{E} \left[ \exp(\sigma(B_s - B_t)) \cdot \exp \left( \sigma B_t - \frac{1}{2} \sigma^2 s \right) | \mathcal{F}_t \right] \\ &= \mathbb{E}[\exp(\sigma(B_s - B_t)) | \mathcal{F}_t] \cdot \mathbb{E} \left[ \exp \left( \sigma B_t - \frac{1}{2} \sigma^2 s \right) | \mathcal{F}_t \right] \\ &= \exp \left( \frac{1}{2} \sigma^2 (s - t) \right) \cdot \exp \left( -\frac{1}{2} \sigma^2 s \right) \cdot \mathbb{E}[\exp(\sigma B_t) | \mathcal{F}_t] \\ &= \exp \left( -\frac{1}{2} \sigma^2 t \right) \cdot \exp(\sigma B_t) \\ &= \exp \left( \sigma B_t - \frac{1}{2} \sigma^2 t \right) = M_t. \end{aligned}$$

Moreover, we consider the expectation of  $M_t$ , namely:

$$\begin{aligned} \mathbb{E}[|M_t|] &= \mathbb{E} \left[ \left| \exp \left( \sigma B_t - \frac{1}{2} \sigma^2 t \right) \right| \right] = \mathbb{E} \left[ \exp \left( \sigma B_t - \frac{1}{2} \sigma^2 t \right) \right] \\ &= \exp \left( -\frac{1}{2} \sigma^2 t \right) \mathbb{E}[\exp(\sigma B_t)] = \exp \left( -\frac{1}{2} \sigma^2 t \right) \exp \left( \frac{1}{2} \sigma^2 t \right) = 1 < +\infty. \end{aligned}$$

Hence, we have shown that  $M_t$  is martingale. □

## IV Problem Set 4

**Problem IV.1.** (Exercise 4.1 on [Øksendal]). Use Itô's formula to write the following stochastic processes  $Y_t$  in the standard form:

$$dY_t = u(t, \omega)dt + v(t, \omega)dB_t$$

for suitable choices of  $u \in \mathbb{R}^n$ ,  $v \in \mathbb{R}^{n \times m}$  and dimensions  $n, m$ :

(a)  $Y_t = B_t^2$ , where  $B_t$  is 1-dimensional.

**Solution.** Here, we note that:

$$Y_t = B_t^2 = \int_0^t ds + 2 \int_0^t B_s dB_s,$$

hence it is in standard form as:

$$dY_t = \boxed{dt + B_t dB_t}.$$

□

(b)  $Y_t = 2 + t + e^{B_t}$ , where  $B_t$  is 1-dimensional.

**Solution.** Here, we may apply **Itô formula**, namely:

$$\begin{aligned} dY_t &= \frac{\partial}{\partial t}[2 + t + e^{B_t}]dt + \frac{\partial}{\partial x}[2 + t + e^{B_t}]dB_t + \frac{1}{2} \frac{\partial^2}{\partial x^2}[2 + t + e^{B_t}](dB_t)^2 \\ &= dt + e^{B_t}dB_t + \frac{1}{2}e^{B_t}dt = \boxed{\left(1 + \frac{1}{2}e^{B_t}\right)dt + e^{B_t}dB_t}. \end{aligned}$$

□

(c)  $Y_t = B_1^2(t) + B_2^2(t)$ , where  $(B_1, B_2)$  is 2-dimensional.

**Solution.** Here, we may apply the **general Itô formula** as:

$$\begin{aligned} dY_t &= \frac{\partial}{\partial t}[B_1^2(t) + B_2^2(t)]dt + \frac{\partial}{\partial B_1}[B_1^2(t) + B_2^2(t)]dB_1 + \frac{\partial}{\partial B_2}[B_1^2(t) + B_2^2(t)]dB_2 + \\ &\quad \frac{1}{2} \frac{\partial^2}{\partial B_1^2}[B_1^2(t) + B_2^2(t)](dB_1)^2 + \frac{1}{2} \frac{\partial^2}{\partial B_2^2}[B_1^2(t) + B_2^2(t)](dB_2)^2 + \frac{\partial^2}{\partial B_1 \partial B_2}[B_1^2(t) + B_2^2(t)](dB_1 dB_2) \\ &= 0dt + 2B_1 dB_1 + 2B_2 dB_2 + dt + dt + 0\delta_{1,2}dt \\ &= \boxed{2dt + 2B_1(t)dB_1(t) + 2B_2(t)dB_2(t)}. \end{aligned}$$

□

(d)  $Y_t = (t_0 + t, B_t)$ , where  $B_t$  is 1-dimensional.

**Solution.** Here, we need to consider the process component-wise, denoted  $Y_t = (Y_t^{(1)}, Y_t^{(2)})$ .

For  $Y_t^{(1)}$ , we have:

$$d(Y_t^{(1)}) = \frac{\partial}{\partial t}[t_0 + t]dt + \frac{\partial}{\partial B_t}[t_0 + t]dB_t + \frac{1}{2} \frac{\partial}{\partial B_t^2}[t_0 + t](dB_t)^2 = dt.$$

For  $Y_t^{(2)}$ , we have:

$$d(Y_t^{(2)}) = \frac{\partial}{\partial t}[B_t]dt + \frac{\partial}{\partial B_t}[B_t]dB_t + \frac{1}{2} \frac{\partial}{\partial B_t^2}[B_t](dB_t)^2 = dB_t.$$

Hence, the process can be written in standard form as:

$$dY_t = \boxed{\begin{pmatrix} 1 \\ 0 \end{pmatrix} dt + \begin{pmatrix} 0 \\ 1 \end{pmatrix} dB_t}.$$

□

(e)  $Y_t = (B_1(t) + B_2(t) + B_3(t), B_2^2(t) - B_1(t)B_3(t))$ , where  $(B_1, B_2, B_3)$  is 3-dimensional.

**Solution.** Again, we shall consider the process component-wise, denoted  $Y_t = (Y_t^{(1)}, Y_t^{(2)})$ . For  $Y_t^{(1)}$ , we have:

$$\begin{aligned} dY_t^{(1)} &= \frac{\partial}{\partial t}[B_1 + B_2 + B_3]dt + \frac{\partial}{\partial B_1}[B_1 + B_2 + B_3]dB_1 + \frac{\partial}{\partial B_2}[B_1 + B_2 + B_3]dB_2 + \frac{\partial}{\partial B_3}[B_1 + B_2 + B_3]dB_3 + \\ &\quad \frac{1}{2} \frac{\partial}{\partial B_1^2}[B_1 + B_2 + B_3](dB_1)^2 + \frac{1}{2} \frac{\partial}{\partial B_2^2}[B_1 + B_2 + B_3](dB_2)^2 + \frac{1}{2} \frac{\partial}{\partial B_3^2}[B_1 + B_2 + B_3](dB_3)^2 + \\ &\quad \frac{\partial}{\partial B_1 \partial B_2}[B_1 + B_2 + B_3]dB_1 dB_2 + \frac{\partial}{\partial B_1 \partial B_3}[B_1 + B_2 + B_3]dB_1 dB_3 + \frac{\partial}{\partial B_2 \partial B_3}[B_1 + B_2 + B_3]dB_2 dB_3 \\ &= dB_1(t) + dB_2(t) + dB_3(t). \end{aligned}$$

For  $Y_t^{(2)}$ , we have:

$$\begin{aligned} dY_t^{(2)} &= \frac{\partial}{\partial t}[B_2^2 - B_1 B_3]dt + \frac{\partial}{\partial B_1}[B_2^2 - B_1 B_3]dB_1 + \frac{\partial}{\partial B_2}[B_2^2 - B_1 B_3]dB_2 + \frac{\partial}{\partial B_3}[B_2^2 - B_1 B_3]dB_3 + \\ &\quad \frac{1}{2} \frac{\partial}{\partial B_1^2}[B_2^2 - B_1 B_3](dB_1)^2 + \frac{1}{2} \frac{\partial}{\partial B_2^2}[B_2^2 - B_1 B_3](dB_2)^2 + \frac{1}{2} \frac{\partial}{\partial B_3^2}[B_2^2 - B_1 B_3](dB_3)^2 + \\ &\quad \frac{\partial}{\partial B_1 \partial B_2}[B_2^2 - B_1 B_3]dB_1 dB_2 + \frac{\partial}{\partial B_1 \partial B_3}[B_2^2 - B_1 B_3]dB_1 dB_3 + \frac{\partial}{\partial B_2 \partial B_3}[B_2^2 - B_1 B_3]dB_2 dB_3 \\ &= -B_3 dB_1 + 2B_2 dB_2 - B_1 dB_3 + (dB_2)^2 = dt - B_3(t)dB_1(t) + 2B_2(t)dB_2(t) - B_1(t)dB_3(t). \end{aligned}$$

Hence, when we combine the process together, we have:

$$dY_t = \boxed{\begin{pmatrix} 0 \\ 1 \end{pmatrix} dt + \begin{pmatrix} 1 \\ -B_3(t) \end{pmatrix} dB_1(t) + \begin{pmatrix} 1 \\ 2B_2(t) \end{pmatrix} dB_2(t) + \begin{pmatrix} 1 \\ -B_1(t) \end{pmatrix} dB_3(t)}.$$

□

**Problem IV.2.** (Exercise 4.2 on [Øksendal]). Use Itô formula to prove that:

$$\int_0^t B_s^2 dB_s = \frac{1}{3} B_t^3 - \int_0^t B_s ds.$$

*Proof.* Here, we write  $B_t^3$  in terms of differential form:

$$dB_t^3 = \frac{\partial}{\partial t}[B_t^3]dt + \frac{\partial}{\partial B_t}[B_t^3]dB_t + \frac{1}{2} \cdot \frac{\partial^2}{\partial B_t^2}[B_t^3](dB_t)^2 = 3B_t dt + 3B_t^2 dB_t,$$

and hence if we were to write them in standard form, we have:

$$B_t^3 = 3 \int_0^t B_s ds + 3 \int_0^t B_s^2 dB_s,$$

and if we were to divide everything by 3 and move around, we have:

$$\int_0^t B_s^2 dB_s = \frac{1}{3} B_t^3 - \int_0^t B_s ds,$$

as desired.  $\square$

**Problem IV.3.** (Exercise 4.3 on [Øksendal]). Let  $X_t, Y_t$  be Itô processes in  $\mathbb{R}$ . Prove that:

$$d(X_t Y_t) = X_t dY_t + Y_t dX_t + dX_t \cdot dY_t.$$

Deduce the following general *integration by parts formula*:

$$\int_0^t X_s dY_s = X_t Y_t - X_0 Y_0 - \int_0^t Y_s dX_s - \int_0^t dX_s \cdot dY_s.$$

*Proof.* Here, we may use the **general Itô formula** to find the differential form as:

$$\begin{aligned} d(X_t Y_t) &= \frac{\partial}{\partial t}[X_t Y_t]dt + \frac{\partial}{\partial X_t}[X_t Y_t]dX_t + \frac{\partial}{\partial Y_t}[X_t Y_t]dY_t + \\ &\quad \frac{1}{2} \frac{\partial^2}{\partial X_t^2}[X_t Y_t](dX_t)^2 + \frac{1}{2} \frac{\partial^2}{\partial Y_t^2}[X_t Y_t](dY_t)^2 + \frac{\partial^2}{\partial X_t \partial Y_t}[X_t Y_t]dX_t dY_t \\ &= Y_t dX_t + X_t dY_t + dX_t \cdot dY_t. \end{aligned}$$

Then, we can write the differential form in standard form:

$$X_t Y_t = X_0 Y_0 + \int_0^t Y_s dX_s + \int_0^t X_s dY_s + \int_0^t dX_s \cdot dY_s.$$

Then, we can move around the terms to get the *integration by parts formula*:

$$\int_0^t X_s dY_s = X_t Y_t - X_0 Y_0 - \int_0^t Y_s dX_s - \int_0^t dX_s \cdot dY_s. \quad \square$$

**Problem IV.4.** (Exercise 4.4 on [Øksendal]). Exponential martingales.

Suppose  $\theta(t, \omega) = (\theta_1(t, \omega), \dots, \theta_n(t, \omega)) \in \mathbb{R}^n$  with  $\theta_k(t, \omega) \in \mathcal{V}[0, T]$  for  $k = 1, \dots, n$ , where  $T \leq \infty$ . Define:

$$Z_t = \exp \left[ \int_0^t \theta(s, \omega) dB(s) - \frac{1}{2} \int_0^t \theta^2(s, \omega) ds \right]; \quad 0 \leq t \leq T,$$

where  $B(s) \in \mathbb{R}^n$  and  $\theta^2 = \theta \cdot \theta$  as the dot product.

(a) Use Itô's formula to prove that:

$$dZ_t = Z_t \theta(t, \omega) dB(t).$$

*Proof.* Here, we first consider another process  $X_t$  such that:

$$dX_t = \theta(t, \omega) dB(t) - \frac{1}{2} \theta^2(t, \omega) dt.$$

Here, we have  $Z_t = \exp(X_t)$ , and we use the Itô formula on a given process:

$$\begin{aligned} dZ_t &= \frac{\partial}{\partial t} [\exp(X_t)] dt + \frac{\partial}{\partial X_t} [\exp(X_t)] dX_t + \frac{1}{2} \frac{\partial}{\partial X_t^2} [\exp(X_t)] (dX_t)^2 \\ &= 0dt + \exp(X_t) dX_t + \frac{1}{2} \exp(X_t) (dX_t)^2 \\ &= \exp(X_t) \left( \theta(t, \omega) dB(t) - \frac{1}{2} \theta^2(t, \omega) dt \right) + \frac{1}{2} \exp(X_t) \left( \theta(t, \omega) dB(t) - \frac{1}{2} \theta^2(t, \omega) dt \right)^2 \\ &= \exp(X_t) \theta(t, \omega) dB(t) - \frac{1}{2} \exp(X_t) \theta^2(t, \omega) dt + \frac{1}{2} \exp(X_t) \theta^2(t, \omega) (dB(t))^2 - \\ &\quad \frac{1}{4} \exp(X_t) \theta^3(t, \omega) dB(t) dt + \frac{1}{8} \exp(X_t) \theta^4(t, \omega) (dt)^2 \\ &= \exp(X_t) \theta(t, \omega) dB(t) - \frac{1}{2} \exp(X_t) \theta^2(t, \omega) dt + \frac{1}{2} \exp(X_t) \theta^2(t, \omega) dt \\ &= \exp(X_t) \theta(t, \omega) dB(t) = Z_t \theta(t, \omega) dB(t), \end{aligned}$$

as desired.  $\square$

(b) Deduce that  $Z_t$  is a martingale for  $t \leq T$ , provided that:

$$Z_t \theta_k(t, \omega) \in \mathcal{V}[0, T] \text{ for } 1 \leq k \leq n.$$

*Proof.* By part (a), we note that  $Z_t$  can be written as:

$$Z_t \theta_k(t, \omega) = \int_0^t Z_s \theta_k(t, \omega) dB(s) = \int_0^t \sum_{k=1}^n Z_s \theta_k(t, \omega) dB_k(s) = \sum_{k=1}^n \int_0^t Z_s \theta_k(t, \omega) dB_k(s).$$

Note that since  $Z_s \theta_k(t, \omega) \in \mathcal{V}[0, T]$  for all  $k$ , the integral  $\int_0^t Z_s \theta_k(t, \omega) dB_k(s)$  must be martingale, and a finite sum of martingale is still martingale.  $\square$

## V Problem Set 5

**Problem V.1.** (Exercise 4.13 on [Øksendal]). Let  $dX_t = u(t, \omega)dt + dB_t$ , where  $u \in \mathbb{R}$  and  $B_t \in \mathbb{R}$ , be an Itô process and assume for simplicity that  $u$  is bounded. Then we know that unless  $u = 0$  the process  $X_t$  is not an  $\mathcal{F}_t$ -martingale. However, it turns out that we can construct an  $\mathcal{F}_t$ -martingale from  $X_t$  by multiplying by a suitable exponential martingale. More precisely, define:

$$Y_t = X_t M_t,$$

where:

$$M_t = \exp \left( - \int_0^t u(r, \omega) dB_r - \frac{1}{2} \int_0^t u^2(r, \omega) dr \right).$$

Use Itô's formula to prove that  $Y_t$  is an  $\mathcal{F}_t$ -martingale.

*Proof.* Here, we think about the Itô formula on  $Y_t$  by considering the product rule:

$$dY_t = d(X_t M_t) = X_t dM_t + M_t dX_t + dX_t dM_t$$

Recall from Problem IV.4(a), we have:

$$dM_t = -M_t u(t, \omega) dB_t,$$

and hence we can continue the product rule as:

$$\begin{aligned} dY_t &= X_t M_t (-u(t, \omega) dB_t) + M_t (u(t, \omega) dt + dB_t) + (u(t, \omega) dt + dB_t) M_t (-u(t, \omega) dB_t) \\ &= -X_t M_t u(t, \omega) dB_t + M_t u(t, \omega) dt + M_t dB_t - M_t u(t, \omega) dt \\ &= M_t (1 - X_t u(t, \omega)) dB_t. \end{aligned}$$

Hence, the Itô formula of  $Y_t$  contains to  $dt$  terms, and recall from Problem IV.4(b), since  $u$  is a Itô process, so  $M_t$  is martingale, thus  $\mathbb{E}[|M_t|] < +\infty$ . Consider for  $X_t$  that:

$$\begin{aligned} \mathbb{E}[|X_t|] &= \mathbb{E} \left[ \left| \int_0^t u(r, \omega) dr + \int_0^t dB_r \right| \right] \\ &\leq \mathbb{E} \left[ \left| \int_0^t u(r, \omega) dr \right| \right] + \mathbb{E} \left[ \left| \int_0^t dB_r \right| \right] \leq \mathbb{E} \left[ \int_0^t |u(r, \omega)| dr \right] + \mathbb{E}[|B_t|] < +\infty, \end{aligned}$$

since  $u(r, \omega)$  is bounded and  $\mathbb{E}[|B_t|^2] = t$ , so we have  $\mathbb{E}[|X_t M_t|] \leq \mathbb{E}[|X_t|] \cdot \mathbb{E}[|M_t|] < +\infty$ , hence have proven that  $Y_t$  is, in fact, a  $\mathcal{F}_t$  martingale.  $\square$

**Problem V.2.** (Exercise 4.16 on [Øksendal]). If  $Y$  is an  $\mathcal{F}_T$ -measurable random variable such that  $\mathbb{E}[|Y|^2] < \infty$ , then the process:

$$M_t := \mathbb{E}[Y | \mathcal{F}_t]; \quad 0 \leq t \leq T$$

is a martingale with respect to  $\{\mathcal{F}_t\}_{0 \leq t \leq T}$ .

(a) Show that  $\mathbb{E}[M_t^2] < \infty$  for all  $t \in [0, T]$ .

*Proof.* Note we have  $\mathcal{F}_t$  as a  $\sigma$ -algebra, so we have:

$$\mathbb{E}[(\mathbb{E}[Y | \mathcal{F}_t])^2] \leq \mathbb{E}[Y^2] < +\infty,$$

as desired.  $\square$

(b) According to the martingale representation theorem, there exists a unique process  $g(t, \omega) \in \mathcal{V}(0, T)$  such that:

$$M_t = \mathbb{E}[M_0] + \int_0^t g(s, \omega) dB(s); \quad t \in [0, T].$$

Find  $g$  in the following cases:

1.  $Y(\omega) = B^2(T)$ .
2.  $Y(\omega) = B^3(T)$ .
3.  $Y(\omega) = \exp(\sigma B(T))$ , where  $\sigma \in \mathbb{R}$  is a constant.

*Hint:* Use that  $\exp(\sigma B(t) - \frac{1}{2}\sigma^2 t)$  is a martingale.

### Solution.

1. Now, we have:

$$M_t = \mathbb{E}[B_T^2 | \mathcal{F}_t].$$

Here, we decompose that:

$$B_T^2 = (B_t + (B_T - B_t))^2 = B_t^2 + 2B_t(B_T - B_t) + (B_T - B_t)^2,$$

so we have the conditional expectation as:

$$\begin{aligned} \mathbb{E}[B_T^2 | \mathcal{F}_t] &= \mathbb{E}[B_t^2 + 2B_t(B_T - B_t) + (B_T - B_t)^2 | \mathcal{F}_t] \\ &= \mathbb{E}[B_t^2 | \mathcal{F}_t] + 2\mathbb{E}[B_t | \mathcal{F}_t]\mathbb{E}[B_T - B_t | \mathcal{F}_t] + \mathbb{E}[(B_T - B_t)^2 | \mathcal{F}_t] \\ &= B_t^2 + 2B_t\mathbb{E}[B_t - B_t] + \mathbb{E}[(B_T - B_t)^2] = B_t^2 + T - t. \end{aligned}$$

Then, we apply the Itô formula and obtain that:

$$dM_t = -dt + 2B_t dB_t + \frac{1}{2} \cdot 2dt = 2B_t dB_t,$$

hence we have  $g(s, \omega) = \boxed{2B_s(\omega)}$ .

2. Now, we have:

$$M_t = \mathbb{E}[B_T^3 | \mathcal{F}_t],$$

and we similarly construct the decomposition as:

$$B_T^3 = (B_t + (B_T - B_t))^3 = B_t^3 + 3B_t^2(B_T - B_t) + 3B_t(B_T - B_t)^2 + (B_T^2 - B_t)^3.$$

Now, we apply the conditional expectation as:

$$\begin{aligned}
 \mathbb{E}[B_T^3 \mid \mathcal{F}_t] &= \mathbb{E}[B_t^3 + 3B_t^2(B_T - B_t) + 3B_t(B_T - B_t)^2 + (B_T^2 - B_t)^3 \mid \mathcal{F}_t] \\
 &= \mathbb{E}[B_t^3 \mid \mathcal{F}_t] + 3\mathbb{E}[B_t^2 \mid \mathcal{F}_t]\mathbb{E}[B_T - B_t \mid \mathcal{F}_t] \\
 &\quad + 3\mathbb{E}[B_t \mid \mathcal{F}_t]\mathbb{E}[(B_T - B_t)^2 \mid \mathcal{F}_t] + \mathbb{E}[(B_T^2 - B_t)^3 \mid \mathcal{F}_t] \\
 &= B_t^3 + 3B_t(T - t) + 3B_t^2 \cdot 0 + T - t = B_t^3 + 3TB_t - 3tB_t.
 \end{aligned}$$

Then, we apply the Itô formula and obtain that:

$$\begin{aligned}
 dM_t &= -3B_t dt + (3B_t^2 + 3T - 3t)dB_t + \frac{1}{2} \cdot 6B_t dt \\
 &= 3(B_t^2 + T - t)dB_t,
 \end{aligned}$$

and hence we have  $g(s, \omega) = \boxed{3(B_t^2 + T - t)}$ .

3. Here, we have:

$$M_t = \mathbb{E}[\exp(\sigma B_T) \mid \mathcal{F}_t],$$

and we consider that:

$$\exp(\sigma B_T) = \exp(\sigma(B_t + (B_T - B_t))) = \exp(\sigma B_t) \exp(\sigma(B_T - B_t)),$$

and we hence have that:

$$\begin{aligned}
 \mathbb{E}[\exp(\sigma B_T) \mid \mathcal{F}_t] &= \mathbb{E}[\exp(\sigma B_t) \exp(\sigma(B_T - B_t)) \mid \mathcal{F}_t] \\
 &= \mathbb{E}[\exp(\sigma B_t) \mid \mathcal{F}_t] \cdot \mathbb{E}[\exp(\sigma(B_T - B_t)) \mid \mathcal{F}_t] \\
 &= \exp(\sigma B_t) \cdot \exp\left(\frac{\sigma^2(T - t)}{2}\right).
 \end{aligned}$$

Hence, we apply Itô formula to obtain that:

$$dM_t = M_t \left(-\frac{\sigma^2}{2}\right) dt + M_t \cdot \sigma dB_t + \frac{1}{2}M_t \cdot \sigma^2 dt = M_t \cdot \sigma dB_t,$$

and hence we have  $g(s, \omega) = \boxed{\sigma \exp(\sigma B_t) \cdot \exp\left(\frac{\sigma^2(T - t)}{2}\right)}$ . □

**Problem V.3.** (Exercise 5.7 on [Øksendal]). The *mean-reverting Ornstein-Uhlenbeck process* is the solution  $X_t$  of the stochastic differential equation:

$$dX_t = (m - X_t)dt + \sigma dB_t,$$

where  $m, \sigma$  are real constants, and  $B_t \in \mathbb{R}$ .

(a) Solve this equation using the integrating factor similar to  $e^t$ .

**Solution.** Here, we multiply by the integration factor that:

$$F_t = \exp(t), \quad \text{and so } dF_t = \exp(t)dt.$$

Then, we consider the product rule as:

$$\begin{aligned} d(F_t X_t) &= F_t dX_t + X_t dF_t + dF_t dX_t \\ &= \exp(t)((m - X_t)dt + \sigma dB_t) + \exp(t)X_t dt + \exp(t)dt((m - X_t)dt + \sigma dB_t) \\ &= \exp(t)m dt + \exp(t)\sigma dB_t. \end{aligned}$$

Thereby, we write the equation in standard form:

$$\begin{aligned} F_t X_t &= F_0 X_0 + m \int_0^t \exp(s)ds + \sigma \int_0^t \exp(s)dB_s = F_0 X_0 + m(\exp(t) - 1) + \sigma \int_0^t \exp(s)dB_s, \\ \exp(t)X_t &= X_0 + m \exp(t) - m + \sigma \int_0^t \exp(s)dB_s, \\ X_t &= \boxed{X_0 \exp(-t) + m - m \exp(-t) + \sigma \int_0^t \exp(s-t)dB_s}. \end{aligned}$$

□

(b) Find  $\mathbb{E}[X_t]$  and  $\text{Var}[X_t] := \mathbb{E}[(X_t - \mathbb{E}[X_t])^2]$ .

**Solution.** For the expectation, we have:

$$\begin{aligned} \mathbb{E}[X_t] &= \mathbb{E} \left[ X_0 \exp(-t) + m - m \exp(-t) + \sigma \int_0^t \exp(s-t)dB_s \right] \\ &= X_0 \exp(-t) + m - m \exp(-t) + \sigma \underbrace{\mathbb{E} \left[ \int_0^t \exp(s-t)dB_s \right]}_{\text{deterministic, 0}} \\ &= \boxed{X_0 \exp(-t) + m - m \exp(-t)}. \end{aligned}$$

For the variance, we hence have:

$$\begin{aligned} \text{Var}[X_t] &:= \mathbb{E}[(X_t - \mathbb{E}[X_t])^2] = \mathbb{E} \left[ \left( \sigma \int_0^t \exp(s-t)dB_s \right)^2 \right] \\ &= \sigma^2 \mathbb{E} \left[ \left( \int_0^t \exp(s-t)dB_s \right)^2 \right] = \sigma^2 \int_0^t \exp(2(s-t))ds \\ &= \sigma^2 \left[ \frac{\exp(2(s-t))}{2} \right]_{s=0}^{s=t} = \sigma^2 \left( \frac{1}{2} - \frac{\exp(-2t)}{2} \right) = \boxed{\frac{\sigma^2}{2}(1 - \exp(-2t))}. \end{aligned}$$

□

**Problem V.4.** (Exercise 5.8 on [Øksendal]). Solve the (2-dimensional) stochastic differential equation:

$$\begin{aligned} dX_1(t) &= X_2(t)dt + \alpha dB_1(t) \\ dX_2(t) &= -X_1(t)dt + \beta dB_2(t) \end{aligned}$$

where  $(B_1(t), B_2(t))$  is 2-dimensional Brownian motion and  $\alpha, \beta$  are constants.

This is a model of a vibrating string subject to a stochastic force.

**Solution.** Here, we denote  $X(t) := (X_1(t), X_2(t))$  and  $B(t) := (B_1(t), B_2(t))$ , so our differential equation becomes:

$$dX(t) = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} X(t)dt + \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix} dB(t).$$

Here, we shall use the integrating factor that:

$$F(t) = \exp \left( t \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \right) = \sum_{n=0}^{\infty} \frac{t^n}{n!} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}^n.$$

We note that the matrix has order 4, that is:

$$\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}^2 = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}, \quad \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}^3 = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \text{ and} \quad \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}^4 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

Hence, we have the matrix exponential as:

$$F(t) = \begin{pmatrix} \sum_{n \in [0]_4} \frac{t^n}{n!} - \sum_{n \in [2]_4} \frac{t^n}{n!} & \sum_{n \in [1]_4} \frac{t^n}{n!} - \sum_{n \in [3]_4} \frac{t^n}{n!} \\ \sum_{n \in [3]_4} \frac{t^n}{n!} - \sum_{n \in [1]_4} \frac{t^n}{n!} & \sum_{n \in [0]_4} \frac{t^n}{n!} - \sum_{n \in [2]_4} \frac{t^n}{n!} \end{pmatrix} = \begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix}.$$

Hence, we have the solution as:

$$\begin{aligned} X(t) &= F(t)X(0) + F(t) \int_0^t F(-s) \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix} B_t ds \\ &= \begin{pmatrix} X_1(0) \cos t + X_2(0) \sin t \\ -X_1(0) \sin t + X_2(0) \cos t \end{pmatrix} + \int_0^t \begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix} \begin{pmatrix} \cos(-s) & \sin(-s) \\ -\sin(-s) & \cos(-s) \end{pmatrix} \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix} \begin{pmatrix} dB_1(s) \\ dB_2(s) \end{pmatrix} \\ &= \begin{pmatrix} X_1(0) \cos t + X_2(0) \sin t \\ -X_1(0) \sin t + X_2(0) \cos t \end{pmatrix} + \int_0^t \begin{pmatrix} \alpha \cos(t-s) & \beta \sin(t-s) \\ -\alpha \sin(t-s) & \beta \cos(t-s) \end{pmatrix} \begin{pmatrix} dB_1(s) \\ dB_2(s) \end{pmatrix}. \end{aligned}$$

Hence, we have the solutions, respectively, as:

$$\begin{aligned} X_1(t) &= \boxed{X_1(0) \cos t + X_2(0) \sin t + \alpha \int_0^t \cos(t-s) dB_1(s) + \beta \int_0^t \sin(t-s) dB_2(s)}, \\ X_2(t) &= \boxed{-X_1(0) \sin t + X_2(0) \cos t - \alpha \int_0^t \sin(t-s) dB_1(s) + \beta \int_0^t \cos(t-s) dB_2(s)}. \end{aligned}$$

□

**Problem V.5.** (Exercise 5.16 on [Øksendal]). For more general nonlinear stochastic differential equation of the form:

$$dX_t = f(t, X_t)dt + c(t)X_t dB_t, \quad X_0 = x, \quad (3)$$

where  $f : \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  and  $c : \mathbb{R} \rightarrow \mathbb{R}$  are given continuous (deterministic functions).

(a) Define the ‘integration factor’:

$$F_t = F_t(\omega) = \exp \left( - \int_0^t c(s) dB_s + \frac{1}{2} \int_0^t c^2(s) ds \right).$$

Show that (3) can be written as:

$$d(F_t X_t) = F_t \cdot f(t, X_t)dt. \quad (4)$$

*Proof.* Here, let’s first derive  $dF_t$  using Itô formula with  $dX_t = \frac{1}{2}c^2(t)dt - c(t)dB_t$ :

$$dF_t = F_t \left( dX_t + \frac{1}{2}(dX_t)^2 \right) = F_t \left( \frac{1}{2}c^2(t)dt - c(t)dB_t \right) + \frac{1}{2}F_t c^2(t)dt = F_t(c^2(t)dt - c(t)dB_t).$$

Therefore, we have the product rule resulting in:

$$\begin{aligned} d(F_t X_t) &= F_t dX_t + X_t dF_t + dF_t dX_t \\ &= F_t(f(t, X_t)dt + c(t)X_t dB_t) + X_t F_t(c^2(t)dt - c(t)dB_t) \\ &\quad + F_t(c^2(t)dt - c(t)dB_t)dB_t(f(t, X_t)dt + c(t)X_t dB_t) \\ &= F_t f(t, X_t)dt, \end{aligned}$$

as desired.  $\square$

(b) Now define:

$$Y_t(\omega) = F_t(\omega)X_t(\omega)$$

so that:

$$X_t = F_t^{-1}Y_t. \quad (5)$$

Deduce that equation (4) gets the form:

$$\frac{dY_t(\omega)}{dt} = F_t(\omega) \cdot f(t, F_t^{-1}(\omega)Y_t(\omega)), \quad Y_0 = x. \quad (6)$$

Note that this is just a *deterministic* differential equation in the function  $t \mapsto Y_t(\omega)$ , for each  $\omega \in \Omega$ . We can therefore solve (6) with  $\omega$  as a parameter to find  $Y_t(\omega)$  and then obtain  $X_t(\omega)$  from (5).

*Proof.* Here, from part (a), we have:

$$d(F_t(\omega)X_t(\omega)) = F_t f(t, X_t)dt = F_t f(t, F_t^{-1}(\omega)X_t(\omega))dt,$$

which completes the proof when dividing both sides by  $dt$ .  $\square$

(c) Apply this method to solve the stochastic differential equation:

$$dX_t = \frac{1}{X_t} dt + \alpha X_t dB_t, \quad X_0 = x > 0,$$

where  $\alpha$  is constant.

**Solution.** Here, we have the integrating factor as:

$$F_t = \exp \left( - \int_0^t \alpha dB_s + \frac{1}{2} \int_0^t \alpha^2 ds \right) = \exp \left( -\alpha \int_0^t dB_s + \frac{\alpha^2}{2} \int_0^t ds \right) = \exp \left( -\alpha B_t + \frac{\alpha}{2} t \right).$$

Then, by (b), let  $Y_t := F_t X_t$ , we have that:

$$\frac{dY_t}{dt} = \exp \left( -\alpha B_t + \frac{\alpha}{2} t \right) \cdot \frac{1}{\exp \left( -\alpha B_t + \frac{\alpha}{2} t \right) Y_t} = Y_t.$$

Hence, this becomes a trivial ODE, that is:

$$Y_t dY_t = dt, \quad \text{and the solution is } Y_t = \sqrt{2t + Y_0^2}.$$

Therefore, we can deduce  $X_t$  as:

$$X_t = \boxed{\exp \left( \alpha B_t - \frac{\alpha}{2} t \right) \cdot \sqrt{2t + x^2}}.$$

□

(d) Apply the method to study the solutions of the stochastic differential equation:

$$dX_t = X_t^\gamma dt + \alpha X_t dB_t, \quad X_0 = x > 0,$$

where  $\alpha$  and  $\gamma$  are constants.

For what values of  $\gamma$  do we get explosion?

**Solution.** Here, we still have the integrating factor as:

$$F_t = \exp \left( - \int_0^t \alpha dB_s + \frac{1}{2} \int_0^t \alpha^2 ds \right) = \exp \left( -\alpha \int_0^t dB_s + \frac{\alpha^2}{2} \int_0^t ds \right) = \exp \left( -\alpha B_t + \frac{\alpha}{2} t \right).$$

Then, by (b), let  $Y_t := F_t X_t$ , we have that:

$$\frac{dY_t}{dt} = \exp \left( -\alpha B_t + \frac{\alpha}{2} t \right) \left( \exp \left( -\alpha B_t + \frac{\alpha}{2} t \right) Y_t \right)^\gamma = \exp \left( \left( -\alpha B_t + \frac{\alpha}{2} t \right) (1 + \gamma) \right) Y_t^\gamma.$$

Again, this is still a separable ODE, and we have:

$$Y_t^{-\gamma} dY_t = \exp \left( \left( -\alpha B_t + \frac{\alpha}{2} t \right) (1 + \gamma) \right) dt.$$

However, we note have a closed-form solution, and the solution is:

$$Y_t = \begin{cases} \left( \int_0^t \exp \left( \left( -\alpha B_s + \frac{\alpha}{2} s \right) (1 + \gamma) \right) ds (1 - \gamma) \right)^{\gamma^{-1}} & \text{when } \gamma \neq 1 \\ \exp \left( \int_0^t \exp \left( \left( -\alpha B_s + \frac{\alpha}{2} s \right) \right) ds \right) & \text{when } \gamma = 1. \end{cases}$$

Hence, we have that:

$$X_t = \begin{cases} \exp(\alpha B_t - \frac{\alpha}{2}t) \left( \int_0^t \exp((-\alpha B_s + \frac{\alpha}{2}s)(1+\gamma)) ds (1-\gamma) \right)^{\gamma-1} & \text{when } \gamma \neq 1 \\ \exp(\alpha B_t - \frac{\alpha}{2}t) \exp \left( \int_0^t \exp((-\alpha B_s + \frac{\alpha}{2}s)) ds \right) & \text{when } \gamma = 1. \end{cases}$$

Note that the solution would explode when  $\gamma > 1$ . □

**Problem V.6.** (Exercise 5.17 on [Øksendal]). **The Gronwall inequality.**

Let  $v(t)$  be a nonnegative function such that:

$$v(t) \leq C + A \int_0^t v(s) ds \text{ for } 0 \leq t \leq T$$

for some constants  $C, A$ , where  $A \geq 0$ . Prove that:

$$v(t) \leq C \exp(At) \text{ for } 0 \leq t \leq T.$$

*Hint:* We may assume  $A \neq 0$ . Define  $w(t) = \int_0^t v(s) ds$ . Then  $w'(t) \leq C + Aw(t)$ . Deduce that:

$$w(t) \leq \frac{C}{A} (\exp(At) - 1)$$

by considering  $f(t) := w(t) \exp(-At)$ .

*Proof.* Consider that  $w(t) = \int_0^t v(s) ds$ , so by using Leibniz rule, its derivative is:

$$w'(t) = v(t) \leq C + A \int_0^t v(s) ds = C + Aw(t).$$

Then, we consider  $f(t) := w(t) \exp(-At)$ , and we take its derivative using the product rule:

$$f'(t) = w'(t) \exp(-At) - Aw(t) \exp(-At) = \exp(-At)(w'(t) - Aw(t)) \leq C \exp(-At).$$

Again, by the Leibniz rule and the previous inequality, while noting  $f(0) = 0$ , we have:

$$f(t) = \int_0^t f'(s) ds \leq \int_0^t C \exp(-As) ds = -\frac{C}{A} (\exp(-At) - 1).$$

Recall that  $\exp(-At)$  is always positive, we can divide both sides by it:

$$w(t) = \frac{f(t)}{\exp(-At)} \leq \frac{-\frac{C}{A} (\exp(-At) - 1)}{\exp(-At)} = \frac{C}{A} (\exp(At) - 1).$$

Thus, we can extend the conclusion to  $v(t)$ , in which:

$$v(t) \leq C + Aw(t) = C + C(\exp(At) - 1) = C \exp(At),$$

which completes the proof. □

**Problem V.7.** Let  $X(t)$  solve the Langevin equation:

$$dX(t) = -\mu X(t)dt + \sigma dB_t$$

and suppose that  $X_0$  is a  $\mathcal{N}\left(0, \frac{\sigma^2}{2\mu}\right)$  random variable. Show that:

$$\mathbb{E}[X(s)X(t)] = \frac{\sigma^2}{2\mu} e^{-\mu|t-s|}, \quad t, s \geq 0.$$

*Proof.* Here, we first solve for the solution of Langevin equation using the integrating factor:

$$F(t) = \exp(\mu t), \quad \text{hence we have } dF(t) = \mu \exp(\mu t)dt.$$

Then, we have the product rule as:

$$\begin{aligned} d(F(t)X(t)) &= F(t)dX(t) + X(t)dF(t) + dF(t)dX(t) \\ &= \exp(\mu t)(-\mu X(t)dt + \sigma dB_t) + \mu \exp(\mu t)X(t)dt \\ &= \sigma \exp(\mu t)dB_t, \end{aligned}$$

and so the solution to the Langevin equation is:

$$F(t)X(t) = F(0)X(0) + \int_0^t \sigma \exp(\mu s)dB_s = X(0) + \sigma \int_0^t \exp(\mu s)dB_s,$$

and hence we have:

$$X(t) = \exp(-\mu t)X(0) + \sigma \int_0^t \exp(\mu(s-t))dB_s.$$

Then, we think about the expectation as:

$$\begin{aligned} \mathbb{E}[X(s)X(t)] &= \mathbb{E}\left[\left(\exp(-\mu t)X(0) + \sigma \int_0^t \exp(\mu(u-t))dB_u\right)\left(\exp(-\mu s)X(0) + \sigma \int_0^s \exp(\mu(u-s))dB_u\right)\right] \\ &= \exp(-\mu(t+s))\mathbb{E}[X^2(0)] + \exp(-\mu t)\sigma\mathbb{E}\left[X(0) \int_0^s \exp(\mu(u-s))dB_u\right] \\ &\quad + \exp(-\mu s)\sigma\mathbb{E}\left[X(0) \int_0^t \exp(\mu(u-t))dB_u\right] + \sigma^2\mathbb{E}\left[\int_0^t \exp(\mu(u-t))dB_u \int_0^s \exp(\mu(u-s))dB_u\right] \\ &= \exp(-\mu(t+s)) \cdot \frac{\sigma^2}{2\mu} + \exp(-\mu t)\sigma\mathbb{E}[X(0)]\mathbb{E}\left[\int_0^s \exp(\mu(u-s))dB_u\right] \\ &\quad + \exp(-\mu s)\sigma\mathbb{E}[X(0)]\mathbb{E}\left[\int_0^t \exp(\mu(u-t))dB_u\right] + \sigma^2\mathbb{E}\left[\int_0^t \exp(\mu(u-t))dB_u \int_0^s \exp(\mu(u-s))dB_u\right] \\ &= \exp(-\mu(t+s)) \cdot \frac{\sigma^2}{2\mu} + \sigma^2\mathbb{E}\left[\int_0^t \exp(\mu(u-t))dB_u \int_0^s \exp(\mu(u-s))dB_u\right]. \end{aligned}$$

Now, the main goal is to evaluate the last integral. Without loss of generality, we assume that  $0 \leq t \leq s$ :

$$\begin{aligned}
& \mathbb{E} \left[ \int_0^t \exp(\mu(u-t)) dB_u \int_0^s \exp(\mu(u-s)) dB_u \right] \\
&= \mathbb{E} \left[ \int_0^t \int_0^s \exp(\mu(u-t)) \exp(\mu(v-s)) dB_v dB_u \right] \\
&= \int_{\Omega} \int_{[0,t]} \int_{[0,s]} \exp(\mu(u+v) - (t+s)) dB_v(\omega) dB_u(\omega) d\omega \\
&= \mathbb{E} \left[ \int_0^t \exp(2\mu v - \mu(t+s)) dB_v(\omega) + \int_t^s dB_u(\omega) \right] \\
&= \exp(-\mu(t+s)) \int_0^t \exp(2\mu v) dv = \frac{1}{2\mu} \exp(-\mu(t+s)) \left[ \exp(2\mu v) \right]_{v=0}^{v=t} \\
&= \frac{1}{2\mu} \exp(-\mu(t+s)) (\exp(2\mu t) - 1).
\end{aligned}$$

When plugged in together, we have:

$$\begin{aligned}
\mathbb{E}[X(s)X(t)] &= \exp(-\mu(t+s)) \cdot \frac{\sigma^2}{2\mu} + \frac{\sigma^2}{2\mu} \exp(-\mu(t+s)) (\exp(2\mu t) - 1) \\
&= \frac{\sigma^2}{2\mu} \exp(-\mu(s-t)).
\end{aligned}$$

Note that since  $s \geq t$  is by our assumption, and it would otherwise be  $t-s$ , and we can conclude by  $|t-s|$ , which result in:

$$\mathbb{E}[X(s)X(t)] = \frac{\sigma^2}{2\mu} \exp(-\mu|t-s|),$$

as desired.  $\square$

**Problem V.8.** Prove that if  $p \geq 2$  and  $X \in \mathcal{V}([0, T])$ , then:

$$\mathbb{E} \left[ \sup_{t \in [0, T]} \left| \int_0^t X_s dB_s \right|^p \right] \leq C_p T^{\frac{p-2}{2}} \mathbb{E} \left[ \int_0^T |X_s|^p ds \right]$$

for some constant  $C_p > 0$  depending only on  $p$ .

*Proof.* First of all, we have Itô isometry that:

$$\mathbb{E} \left[ \left| \int_0^t X_s dB_s \right|^2 \right] = \mathbb{E} \left[ \int_0^t |X_s|^2 ds \right].$$

Given the absolute value, we have non-negativity, and hence:

$$\mathbb{E} \left[ \sup_{t \in [0, T]} \left| \int_0^t X_s dB_s \right|^2 \right] \leq \mathbb{E} \left[ \int_0^T |X_s|^2 ds \right].$$

This part is partially adapted from [external source](#). Here, we consider the function  $\varphi$ :

$$\varphi(x) = |x|^p.$$

Here, we have:

$$\varphi'(x) = \operatorname{sgn}(x)p|x|^{p-1}, \text{ and } \varphi''(x) = p(p-1)|x|^{p-2} \text{ a.a.}$$

Note that  $\int_0^t X_s dB_s =: M$  is a martingale, and we denote its supremum by  $M^*$ , and by Martingale representation theorem, it can be written as:

$$M^p = \int_0^T \operatorname{sgn}(M_s) p|M_s|^{p-1} dM_s + \frac{1}{2} \int_0^T p(p-1)|x|^{p-2} (dM_s)^2.$$

In particular, the expectation is:

$$\mathbb{E}[|M|^p] \leq \frac{p(p-1)}{2} \mathbb{E}[|M^*|^{p-2} |M|^2].$$

Then, to utilize the Hölder inequality with  $q = \frac{p}{p-2}$ , we have:

$$\mathbb{E}[|M^*|^{p-2} |M|^2] \leq \mathbb{E}[|M^*|^p]^{\frac{p-2}{p}} \mathbb{E}[|M|^p]^{\frac{p}{2}} \cdot T^{\frac{p-2}{p} \cdot \frac{p}{2}}$$

Then, we have:

$$\mathbb{E}[|M^*|^p] \leq C_p T^{\frac{p-2}{2}} \mathbb{E}[|X_s|^p].$$

□

## VI Problem Set 6

**Problem VI.1.** Let us consider the one-dimensional SDE:

$$dX_t = \left( \sqrt{1 + X_t^2} + \frac{1}{2}X_t \right) dt + \sqrt{1 + X_t^2} dB_t, \quad X_0 = x \in \mathbb{R}.$$

(a) Does this equation admit strong solutions?

**Solution.** Here, this equation admits strong solution. First, we denote:

$$b(t, x) = \sqrt{1 + x^2} + \frac{1}{2}x \quad \text{and} \quad \sigma(t, x) = \sqrt{1 + x^2}.$$

We can verify this by showing that it satisfies the existence and uniqueness theorem for SDEs.

- **Linear growth:** We note that:

$$\begin{aligned} |b(t, x)| + |\sigma(t, x)| &= \left| \sqrt{1 + x^2} + \frac{1}{2}x \right| + \left| \sqrt{1 + x^2} \right| \\ &\leq \frac{1}{2}|x| + 2\left| \sqrt{1 + x^2} \right| \leq \frac{1}{2}(1 + |x|) + 2(1 + |x|) = \frac{5}{2}(1 + |x|). \end{aligned}$$

- **Lipschitz condition:** We note that the derivative of  $\sigma(t, x)$  is:

$$\left| \frac{d\sigma}{dx}(t, x) \right| = \frac{|x|}{\sqrt{1 + x^2}} < \frac{|x|}{\sqrt{x^2}} = 1.$$

Hence,  $\sigma(t, x)$  must be Lipschitz, since if we assume that  $|\sigma(t, x) - \sigma(t, y)| > |x - y|$ , then by the Cauchy's mean value theorem, we have:

$$\frac{|\sigma(t, x) - \sigma(t, y)|}{|x - y|} > 1 \text{ which implies that there exists some } \xi \in [x, y] \text{ such that } \frac{d\sigma}{dx}(t, \xi) > 1,$$

which is a contradiction, so we have:

$$|b(t, x) - b(t, y)| + |\sigma(t, x) - \sigma(t, y)| \leq 2|\sigma(t, x) - \sigma(t, y)| + \frac{1}{2}|x - y| \leq \frac{5}{2}|x - y|.$$

- **Initial condition:** Note that  $X_0 = x \in \mathbb{R}$  is a constant, which is independent of the Brownian motion, and  $\mathbb{E}[|x|^2] = x^2 < \infty$ .

Therefore, the equation satisfies the **existence and uniqueness theorem**. Hence, the equation admits strong solution.  $\square$

(b) Let  $Y_t = \log \left( \sqrt{1 + X_t^2} + X_t \right)$ . Find the SDE  $Y_t$  satisfied.

**Solution.** Here, we want to use the Itô formula, here we consider the function:

$$g(x) = \log \left( \sqrt{1 + x^2} + x \right).$$

Here, we take the partial derivatives with respect to  $x$  for  $g(x)$ , where we note that:

$$\begin{aligned} g'(x) &= \frac{\frac{x}{\sqrt{1+x^2}} + 1}{\sqrt{1+x^2} + x} = \frac{\frac{x}{\sqrt{1+x^2}} + 1}{\sqrt{1+x^2} + x} \cdot \frac{\sqrt{1+x^2} - x}{\sqrt{1+x^2} - x} \\ &= \frac{x + \sqrt{1+x^2} - \frac{x^2}{\sqrt{1+x^2}} - x}{1 + x^2 - x^2} = \sqrt{1+x^2} - \frac{x^2}{\sqrt{1+x^2}} = (1+x^2)^{-\frac{1}{2}}, \\ g''(x) &= -\frac{1}{2}(1+x^2)^{-\frac{3}{2}} \cdot (2x) = -x(1-x^2)^{-\frac{3}{2}}. \end{aligned}$$

Then, we have:

$$\begin{aligned} dY_t &= \frac{\partial}{\partial t}g(X_t)dt + \frac{\partial}{\partial x}g(X_t)dX_t + \frac{1}{2}\frac{\partial^2}{\partial x^2}g(X_t)(dX_t)^2 \\ &= \frac{1}{\sqrt{1+X_t^2}}dX_t - \frac{1}{2}\frac{X_t}{(1+X_t^2)^{\frac{3}{2}}}(dX_t)^2 \\ &= \frac{1}{\sqrt{1+X_t^2}} \left[ \left( \sqrt{1+X_t^2} + \frac{1}{2}X_t \right) dt + \sqrt{1+X_t^2}dB_t \right] \\ &\quad - \frac{1}{2}\frac{X_t}{(1+X_t^2)^{\frac{3}{2}}} \left[ \left( \sqrt{1+X_t^2} + \frac{1}{2}X_t \right) dt + \sqrt{1+X_t^2}dB_t \right]^2 \\ &= dt + \frac{X_t}{2\sqrt{1+X_t^2}}dt + dB_t - \frac{1}{2}\frac{X_t}{(1+X_t^2)^{\frac{3}{2}}} \left( 1+X_t^2 \right) dt \\ &= dt + \frac{1}{2}\frac{X_t}{\sqrt{1+X_t^2}}dt + dB_t - \frac{1}{2}\frac{X_t}{\sqrt{1+X_t^2}}dt = dt + dB_t. \end{aligned}$$

Hence,  $Y_t$  satisfies that  $dY_t = dt + dB_t$ . □

(c) Deduce an explicit solution for  $X_t$ .

**Solution.** To find the solution, we have:

$$Y_t = Y_0 + \int_0^t ds + \int_0^t dB_s = Y_0 + t + B_t.$$

Also, we note that:

$$Y_0 = \log(\sqrt{1+x^2} + x),$$

so we have:

$$Y_t = \log(\sqrt{1+x^2} + x) + t + B_t.$$

Then, we can write  $Y_t$  as function of  $X_t$ :

$$\log \left( \sqrt{1+X_t^2} + X_t \right) = \log(\sqrt{1+x^2} + x) + t + B_t.$$

By taking the exponential on both sides, we have:

$$\sqrt{1+X_t^2} + X_t = e^t e^{B_t} + (\sqrt{1+x^2} + x),$$

and by some arithmetic deductions, we get to that:

$$X_t = \boxed{\frac{\left(e^t e^{B_t} + (\sqrt{1+x^2} + x)\right)^2 - 1}{2\left(e^t e^{B_t} + (\sqrt{1+x^2} + x)\right)}}.$$

↓

**Problem VI.2.** Let us consider the one-dimensional SDE:

$$dX_t = b(X_t)dt + \sigma(X_t)dB_t, \quad X_0 = x \in \mathbb{R}.$$

Assume that  $b, \sigma$  satisfies the Lipschitz condition and linear growth condition. Moreover, assume  $\sigma$  is continuous differentiable with  $|\sigma'(x)| \leq C < \infty$  and  $\sigma(x) \geq \delta > 0$  for all  $x \in \mathbb{R}$ .

(a) Consider  $f(x) = \int_0^x \frac{1}{\sigma(y)} dy$  and the process  $Y_t = f(X_t)$ . Find the SDE  $Y_t$  satisfies.

**Solution.** Here, by the **Leibniz rule**, we have that:

$$\frac{\partial f}{\partial x} = \frac{1}{\sigma(x)} \quad \text{and} \quad \frac{\partial^2 f}{\partial x^2} = -\frac{\sigma'(x)}{(\sigma(x))^2}.$$

Then, we use Itô formula to derive that:

$$\begin{aligned} dY_t &= \frac{\partial}{\partial t} f(X_t)dt + \frac{\partial}{\partial x} f(X_t)dX_t + \frac{1}{2} \frac{\partial^2}{\partial x^2} f(X_t)(dX_t)^2 \\ &= \frac{1}{\sigma(X_t)} dX_t - \frac{1}{2} \frac{\sigma'(x)}{(\sigma(x))^2} (dX_t)^2 \\ &= \frac{1}{\sigma(X_t)} [b(X_t)dt + \sigma(X_t)dB_t] - \frac{1}{2} \frac{\sigma'(x)}{(\sigma(x))^2} [b(X_t)dt + \sigma(X_t)dB_t]^2 \\ &= \frac{b(X_t)}{\sigma(X_t)} dt + dB_t - \frac{1}{2} \frac{\sigma'(X_t)}{(\sigma(X_t))^2} (\sigma(X_t))^2 dt = \left( \frac{b(X_t)}{\sigma(X_t)} - \frac{1}{2} \sigma'(X_t) \right) dt + dB_t. \end{aligned}$$

Hence, the SDE that  $Y_t$  satisfies is:

$$\boxed{dY_t = \left( \frac{b(X_t)}{\sigma(X_t)} - \frac{1}{2} \sigma'(X_t) \right) dt + dB_t}.$$

↓

(b) Prove that, under the assumption in (a), the filtration  $\mathcal{H}_t = \sigma(\{X_s\}_{0 \leq s \leq t})$  coincides with the natural filtration  $\mathcal{F}_t = \sigma(\{B_s\}_{0 \leq s \leq t})$ .

*Proof.* Here, we want to show the two inclusions for the filtrations.

- ( $\mathcal{H}_t \subset \mathcal{F}_t$ :) Note that by definition:

$$dX_t = b(X_t)dt + \sigma(X_t)dB_t, \quad X_0 = x \in \mathbb{R},$$

where  $b, \sigma$  satisfies the Lipschitz condition and linear growth condition. Also we have  $X_0 = x \in \mathbb{R}$  independent of  $B_t$  in which  $\mathbb{E}[|x|^2] = x^2 < \infty$ . Hence, the SDE satisfies the existence and uniqueness theorem, and so  $X_t$  is adapted to  $\sigma(\{B_s\}_{0 \leq s \leq t})$ , and hence  $\mathcal{H}_t \subset \mathcal{F}_t$ .

- ( $\mathcal{F}_t \subset \mathcal{H}_t$ :) Here, recall from part (a), we have:

$$dB_t = \left( \frac{b(X_t)}{\sigma(X_t)} - \frac{1}{2}\sigma'(X_t) \right) dt + dY_t.$$

Clearly, 1 satisfies the linear growth and Lipschitz condition, and we need to verify the first part, in which we denote:

$$\varphi(x) = \frac{b(x)}{\sigma(x)} - \frac{1}{2}\sigma'(x).$$

For the **linear growth** condition, we have that:

$$|\varphi(x)| \leq \frac{|b(x)|}{|\sigma(x)|} + \frac{1}{2}|\sigma'(x)| \leq \frac{B(1+|x|)}{\delta} + \frac{1}{2}C \leq \left( \frac{B}{\delta} + \frac{C}{2} \right) (1+|x|).$$

Note that we do **not** need Lipschitz condition, since we just need existence of a strong solution so that  $\mathcal{F}_t$  is  $\mathcal{M}_t := \sigma(\{Y_s\}_{t \leq s})$ -adapted.

Also, note that  $f$  is monotonic, so it is injective, hence admitting a left-inverse  $f^{-1}$ . Note that  $\sigma$  is measurable,  $f$  is also measurable, so does the left-inverse  $f^{-1}$ . Hence,  $\mathcal{M}_t = \mathcal{H}_t$ , and so  $\mathcal{F}_t \subset \mathcal{H}_t$ .

With both inclusions, we have  $\mathcal{H}_t = \mathcal{F}_t$ , as desired. □

## VII Problem Set 7

**Problem VII.1.** (Exercise 7.1 on [Øksendal]). Find the generator of the following Itô diffusions:

(a)  $dX_t = \mu X_t dt + \sigma dB_t$  (The Ornstein-Uhlenbeck process), where  $B_t \in \mathbb{R}$ , and  $\mu, \sigma$  are constants.

**Solution.** Here, let  $f \in C_0^2(\mathbb{R})$  be arbitrary, and we write the process as:

$$dX_t = \underbrace{\mu X_t}_{b(X_t)} dt + \underbrace{\sigma}_{\sigma(X_t)} dB_t,$$

and we have the infinitesimal generator as:

$$Af(x) = \mu x \frac{\partial f}{\partial x} + \frac{1}{2} \sigma^2 \frac{\partial^2 f}{\partial x^2} = \boxed{\mu x f'(x) + \frac{1}{2} \sigma^2 f''(x)}.$$

(b)  $dX_t = r X_t dt + \alpha X_t dB_t$  (The geometric Brownian motion), where  $B_t \in \mathbb{R}$ , and  $r, \alpha$  are constants.

**Solution.** Again, let  $f \in C_0^2(\mathbb{R})$  be arbitrary, and we write the process as:

$$dX_t = \underbrace{r X_t}_{b(X_t)} dt + \underbrace{\alpha X_t}_{\sigma(X_t)} dB_t,$$

and we have the infinitesimal generator as:

$$Af(x) = r x \frac{\partial f}{\partial x} + \frac{1}{2} (\alpha x)^2 \frac{\partial^2 f}{\partial x^2} = \boxed{r x f'(x) + \frac{1}{2} \alpha^2 x^2 f''(x)}.$$

(c)  $dY_t = r dt + \alpha Y_t dB_t$ , where  $B_t \in \mathbb{R}$ , and  $r, \alpha$  are constants.

**Solution.** Once again, let  $f \in C_0^2(\mathbb{R})$  be arbitrary, and we write the process as:

$$dY_t = \underbrace{r}_{b(Y_t)} dt + \underbrace{\alpha Y_t}_{\sigma(Y_t)} dB_t,$$

and we have the infinitesimal generator as:

$$Af(x) = r \frac{\partial f}{\partial x} + \frac{1}{2} (\alpha x)^2 \frac{\partial^2 f}{\partial x^2} = \boxed{r f'(x) + \frac{1}{2} \alpha^2 x^2 f''(x)}.$$

(d)  $dY_t = \begin{pmatrix} dt \\ dX_t \end{pmatrix}$ , where  $X_t$  is as in (a).

**Solution.** While again, let  $f \in C_0^2(\mathbb{R}^2)$  be arbitrary, and we write the process as:

$$dY_t = \begin{pmatrix} dt \\ \mu X_t dt + \sigma dB_t \end{pmatrix} = \underbrace{\begin{pmatrix} 1 \\ \mu X_t \end{pmatrix}}_{b(X_t)} dt + \underbrace{\begin{pmatrix} 0 \\ \sigma \end{pmatrix}}_{\sigma(X_t)} dB_t,$$

and we have the infinitesimal generator as:

$$Af(x_1, x_2) = \boxed{\frac{\partial f}{\partial x_1} + \mu x_2 \frac{\partial f}{\partial x_2} + \frac{1}{2} \sigma^2 \frac{\partial^2 f}{\partial x_2^2}}.$$

□

(e)  $\begin{pmatrix} dX_1 \\ dX_2 \end{pmatrix} = \begin{pmatrix} 1 \\ X_2 \end{pmatrix} dt + \begin{pmatrix} 0 \\ e^{X_1} \end{pmatrix} dB_t$ , where  $B_t \in \mathbb{R}$ .

**Solution.** Even again, let  $f \in C_0^2(\mathbb{R}^2)$  be arbitrary, and we write the process as:

$$\begin{pmatrix} dX_1 \\ dX_2 \end{pmatrix} = \underbrace{\begin{pmatrix} 1 \\ X_2 \end{pmatrix}}_{b(X_1, X_2)} dt + \underbrace{\begin{pmatrix} 0 \\ e^{X_1} \end{pmatrix}}_{\sigma(X_1, X_2)} dB_t,$$

and we have the infinitesimal generator as:

$$Af(x_1, x_2) = \boxed{\frac{\partial f}{\partial x_1} + x_2 \frac{\partial f}{\partial x_2} + \frac{1}{2} e^{2x_1} \frac{\partial^2 f}{\partial x_2^2}}.$$

□

**Problem VII.2.** (Exercise 7.2 on [Øksendal]). Find an Itô diffusion (i.e., write down the stochastic differential equation for it) whose generator is the following:

(a)  $Af(x) = f'(x) + f''(x); f \in C_0^2(\mathbb{R})$ .

**Solution.** Here, we reversely construct that:

$$dX_t = dt + \sqrt{2} dB_t.$$

□

(b)  $Af(t, x) = \frac{\partial f}{\partial t} + cx \frac{\partial f}{\partial x} + \frac{1}{2} \alpha^2 x^2 \frac{\partial^2 f}{\partial x^2}; f \in C_0^2(\mathbb{R}^2)$ , where  $c, \alpha$  are constants.

**Solution.** Again, we reversely construct that:

$$dX_t = \boxed{\begin{pmatrix} 1 \\ cX_t^{(2)} \end{pmatrix} dt + \begin{pmatrix} 0 \\ \alpha X_t^{(2)} \end{pmatrix} dB_t}.$$

□

$$(c) \quad Af(x_1, x_2) = 2x_2 \frac{\partial f}{\partial x_1} + \log(1 + x_1^2 + x_2^2) \frac{\partial f}{\partial x_2} + \frac{1}{2}(1 + x_1^2) \frac{\partial^2 f}{\partial x_1^2} + x_1 \frac{\partial^2 f}{\partial x_1 \partial x_2} + \frac{1}{2} \cdot \frac{\partial^2 f}{\partial x_2^2}, \quad f \in C_0^2(\mathbb{R}^2).$$

**Solution.** Once again, we reversely construct the  $\sigma\sigma^\top$  matrix as:

$$\sigma\sigma^\top = \begin{pmatrix} 1 + x_1^2 & x_1 \\ x_1 & 1 \end{pmatrix}.$$

Note that  $\sqrt{1 + x_1^2} \cdot \sqrt{1}$  is not the same as the diagonals, so  $\sigma$  must be a 2-by-2 matrix.

Suppose  $\sigma = \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix}$ , then we have:

$$\sigma\sigma^\top = \begin{pmatrix} a^2 + b^2 & ac + bd \\ ac + bd & c^2 + d^2 \end{pmatrix}$$

and we have a candidate of  $\sigma$  as:

$$\sigma = \begin{pmatrix} 1 & x_1 \\ 0 & 1 \end{pmatrix}$$

Hence, we have:

$$dX_t = \left( \begin{pmatrix} 2X_t^{(2)} \\ \log \left( 1 + X_t^{(1)2} + X_t^{(2)2} \right) \end{pmatrix} dt + \begin{pmatrix} 1 & X_1 \\ 0 & 1 \end{pmatrix} dB_t \right).$$

□

## VIII Problem Set 8

**Problem VIII.1.** (Exercise 7.7 on [Øksendal]). Let  $B_t$  be Brownian motion on  $\mathbb{R}^n$  starting at  $x \in \mathbb{R}^n$  and let  $D \subset \mathbb{R}^n$  be an open ball centered at  $x$ .

(a) Prove that the harmonic measure  $\mu_D^x$  of  $B_t$  is rotation invariant (about  $x$ ) on the sphere  $\partial D$ . Conclude that  $\mu_D^x$  coincides with normalized surface measure  $\sigma$  on  $\partial D$ .

*Proof.* Without loss of generality, we suppose  $x = 0$ , since the harmonic measure and Brownian motion is translational invariant.

First, we want to show that the Brownian motion is invariant with rotations. Suppose  $U \in \mathbb{R}^{n \times n}$  such that  $UU^\top = \text{Id}$ . Hence, we have  $\det U = 1$ , and so when we have the change of variable  $p \mapsto U \cdot p$ , the probability measure is the same, so the rotation of a Brownian motion is still a Brownian motion.

Now, as we consider the definition of the harmonic measure of some  $F \in \partial D$ , we have that:

$$\mu_D^0(F) := Q^0[B_{\tau_D} \in F],$$

and consider a rotation centered at 0 as  $U$ , we then have:

$$\mu_D^0(U \cdot F) := Q^0[B_{\tau_D} \in U \cdot F] = Q^0[U \cdot B_{\tau_D} \in F] = Q^0[B_{\tau_D} \in F] = \mu_D^0(F),$$

as desired. Moreover, consider that the harmonic measure  $\mu_D^x$  of  $B_t$  is rotational invariant about  $\partial D$ , for any point  $d, d' \in \partial D$ , we have that  $\mu_D^x(d) = \mu_D^x(d')$  so the measure is uniformly distributed on the surface, and  $\mu_D(\partial D) = 1$ . Hence, it coincides with the normalized surface measure  $\omega$  on  $\partial D$ .  $\square$

(b) Let  $\phi$  be a bounded measurable function on a bounded open set  $W \subset \mathbb{R}^n$  and define:

$$u(x) = \mathbb{E}^x[\phi(B_{\tau_W})] \quad \text{for } x \in W.$$

Prove that  $u$  satisfies the classical mean value property:

$$u(x) = \int_{\partial D} u(y) d\sigma(y) \tag{7}$$

for all balls  $D$  centered at  $x$  with  $\overline{D} \subset W$ .

*Proof.* Here, we have  $\phi \in L^1(W)$ , so we have that:

$$u(x) = \int_{\partial D} u(y) d\mu_D^x(y) = \int_{\partial D} u(y) d\sigma(y),$$

since  $\mu_D^x$  coincides with normalized surface measure  $\sigma$ .  $\square$

(c) Let  $W$  be as in (b) and let  $w : W \rightarrow \mathbb{R}$  be *harmonic* in  $W$ , i.e.:

$$\Delta w := \sum_{i=1}^n \frac{\partial^2 w}{\partial x_i^2} = 0 \quad \text{in } W.$$

Prove that  $w$  satisfies the classical mean value property (7).

*Proof.* Here, recall Green's formula for Harmonic PDE, we set the problem as:

$$\begin{cases} \Delta w = 0, & \text{in } W, \\ w(x) = g(x), & \text{on } \partial W, \end{cases}$$

where we assume that  $g(x)$  is bounded and measurable function on  $W$ .

Then, we have the model that  $\mathbb{E}[g(B_t^x(\omega))] = u(x)$ , and naturally by (b), we have:

$$w(x) = \int_{\partial D} w(y) d\sigma(y).$$

□

**Problem VIII.2.** (Exercise 7.10 on [Øksendal]). Let  $X_t$  be the geometric Brownian motion:

$$dX_t = rX_t dt + \alpha X_t dB_t.$$

Find  $\mathbb{E}^x[X_T | \mathcal{F}_t]$  for  $t \leq T$  by different approaches.

(a) Using the Markov property.

**Solution.** Here, we use the **Markov property** so that:

$$\begin{aligned} \mathbb{E}^x[X_{t+(T-t)} | \mathcal{F}_t] &= \mathbb{E}^{X_t}[X_{T-t}] = \mathbb{E}[X_t] \cdot \mathbb{E}\left[\exp\left(\left(r - \frac{\alpha^2}{2}\right)t + \alpha B_t\right)\right] \\ &= X_t \exp(r(T-t)) = x \exp(rt) \exp(r(T-t)) = \boxed{x \exp(rt)}. \end{aligned}$$

□

(b) Writing  $X_t = xe^{rt} M_t$ , where:

$$M_t = \exp\left(\alpha B_t - \frac{1}{2}\alpha^2 t\right) \quad \text{is a martingale.}$$

**Solution.** Here, we can write the expectation as:

$$\begin{aligned} \mathbb{E}^x[X_T | \mathcal{F}_t] &= \mathbb{E}^x[xe^{rT} M_T | \mathcal{F}_t] = xe^{rT} \mathbb{E}^x[M_T | \mathcal{F}_t] \\ &= x \exp(rt) \cdot M_t = \exp(r(T-t)) X_t = \boxed{x \exp(rt)}. \end{aligned}$$

□

**Problem VIII.3.** (Exercise 8.1 on [Øksendal]). Let  $\Delta$  denote the Laplace operator on  $\mathbb{R}^n$ .

(a) Write down, in terms of Brownian motion, a bounded solution  $g$  of the Cauchy problem:

$$\begin{cases} \frac{\partial g(t, x)}{\partial t} - \frac{1}{2} \Delta_x g(t, x) = 0, & \text{for } t > 0, x \in \mathbb{R}^n, \\ g(0, x) = \phi(x), \end{cases}$$

where  $\phi \in C_0^2$  is given. (From general theory it is known that the solution is unique.)

**Solution.** Here, since  $\phi \in C_0^2$ , we know that  $\phi$  is lower-bounded. Then, we consider the Itô diffusion:

$$dX_t = 0dt + \text{Id } dB_t = dB_t.$$

Then, we have the generator of the Itô diffusion as:

$$Af = \frac{1}{2} \sum_{i=1}^n \frac{\partial f}{\partial x_i^2} = \Delta_x f \quad \text{for } f \in C^2(\mathbb{R}^n).$$

Hence, we can use **Feynman-Kac Formula** that:

$$g(t, x) = \mathbb{E}^x \left[ \exp \left( - \int_0^t 0ds \right) \phi(X_t) \right] = \boxed{\mathbb{E}^x[\phi(B_t)]}.$$

□

(b) Let  $\psi \in C_b(\mathbb{R}^n)$  and  $\alpha > 0$ . Find a bounded solution  $u$  of the equation:

$$\left( \alpha - \frac{1}{2} \Delta \right) u = \psi \quad \text{in } \mathbb{R}^n.$$

Prove that the solution is unique.

*Proof.* Here, we note that we want to create the same Itô diffusion:

$$dX_t = 0dt + \text{Id } dB_t = dB_t.$$

Then, we have the generator of the Itô diffusion as:

$$Af = \frac{1}{2} \sum_{i=1}^n \frac{\partial f}{\partial x_i^2} = \Delta_x f \quad \text{for } f \in C^2(\mathbb{R}^n).$$

Then, we can use **Feynman-Kac Formula** that:

$$u(t, x) = \mathbb{E}^x \left[ \exp \left( - \int_0^t \psi(X_s) ds \right) \right] = \mathbb{E}^x \left[ \exp \left( - \int_0^t \psi(B_s) ds \right) \right],$$

and the solution is unique for a given initial condition by Feynman-Kac. □

**Problem VIII.4.** (Exercise 8.7 on [Øksendal]). Let  $X_t$  be a sum of Itô integrals of the form:

$$X_t = \sum_{k=1}^n \int_0^t v_k(s, \omega) dB_k(s),$$

where  $(B_1, \dots, B_n)$  is  $n$ -dimensional Brownian motion. Assume that:

$$\beta_t := \int_0^t \sum_{k=1}^n v_k^2(s, \omega) ds \rightarrow \infty \quad \text{as } t \rightarrow \infty \text{ a.s.}$$

Prove that:

$$\limsup_{t \rightarrow \infty} \frac{X_t}{\sqrt{2\beta_t \log \log \beta_t}} = 1 \quad \text{a.s.}$$

*Hint:* Use the law of iterated logarithm.

*Proof.* Here, we consider the differential form:

$$dX_t = \sum_{k=1}^n v_k(s, \omega) dB_k(t).$$

Then, we note that this is a 1-dimensional Brownian motion, and the time change is:

$$\beta_t = \int_0^t \sum_{k=1}^n v_k^2(s, \omega) ds.$$

With this time change, we can consider:

$$\limsup_{t \rightarrow \infty} \frac{X_t}{\sqrt{2\beta_t \log \log \beta_t}} = \limsup_{t \rightarrow \infty} \frac{B_t}{\sqrt{2t \log \log t}} = 1$$

almost surely by the law of iterated logarithm.  $\square$

**Problem VIII.5.** Find a solution to the following PDE:

(a)

$$\begin{cases} \frac{\partial}{\partial t} u(t, x) + bx \frac{\partial}{\partial x} u(t, x) + \frac{\sigma^2}{2} \frac{\partial^2}{\partial x^2} u(t, x) = 0, & x \in \mathbb{R}, t \in (0, T); \\ u(T, x) = x, & x \in \mathbb{R}. \end{cases}$$

**Solution.** Here, we need to think about the process for the SDE, as follows:

$$dX_t = bX_t dt + \sigma dB_t,$$

so we have the Itô generator as:

$$Af = bx \frac{\partial f}{\partial x} + \frac{1}{2} \sigma^2 \frac{\partial^2 f}{\partial x^2}.$$

However, note that  $x$  is not lower bounded, so we cannot use the **Feynman-Kac** backward equation, directly, but we can think of a mollifier for  $\epsilon < 0$  that:

$$\begin{cases} \frac{\partial}{\partial t} u^{(\epsilon)}(t, x) + bx \frac{\partial}{\partial x} u^{(\epsilon)}(t, x) + \frac{\sigma^2}{2} \frac{\partial^2}{\partial x^2} u^{(\epsilon)}(t, x) = 0, & x \in \mathbb{R}, t \in (0, T); \\ u^{(\epsilon)}(T, x) = \max\{\epsilon, x\}, & x \in \mathbb{R}. \end{cases}$$

Here, we consider the solution as:

$$\mathbb{E}^x [\max\{\epsilon, X_T\}] \rightarrow \boxed{\mathbb{E}^x[X_T]},$$

where  $X_t$  is the solution to the OU process.  $\square$

(b) What if the boundary condition was replaced by  $u(T, x) = x^2$ .

**Solution.** Then, we use the **backward Feynman-Kac Formula**, since  $x^2$  is bounded below, so that:

$$u(t, x) = \boxed{\mathbb{E}^x [X_T^2]},$$

where  $X_t$  is the solution to the OU process.  $\square$

**Problem VIII.6.** (Exercise 8.11 on [Øksendal]).

(a) Let  $Y(t) = t + B(t)$  for  $t \geq 0$ . For each  $T > 0$ , find a probability measure  $Q_T$  on  $\mathcal{F}_T$  such that  $Q_T \sim \mathbb{P}$  and  $\{Y(t)\}_{t \leq T}$  is Brownian motion with respect to  $Q_T$ . Use:

$$M_T d\mathbb{P} = M_t d\mathbb{P} \quad \text{on } \mathcal{F}_t^{(n)}; t \leq T \text{ when } M \text{ is a martingale}$$

to prove that there exists a probability measure  $Q$  on  $\mathcal{F}_\infty$  such that:

$$Q|_{\mathcal{F}_T} = Q_T \quad \text{for all } T > 0.$$

**Solution.** Here, we write the expression as:

$$dY(t) = \underbrace{1}_{a(t, \omega)} dt + dB(t),$$

and hence we have the martingale:

$$M_t = \exp \left( - \int_0^t dB_s - \frac{1}{2} \int_0^t ds \right) = \exp \left( -B(t) - \frac{1}{2} t \right),$$

and hence by **Girsanov theorem I**, we have:

$$d\mathbb{Q}(\omega) = \exp\left(-B(T) - \frac{1}{2}T\right) d\mathbb{P}(\omega),$$

while  $Y(t)$  is a Brownian motion with respect to  $\mathbb{Q}_T$  for  $0 \leq t \leq T$ .

Note that  $M_t$  is martingale, hence we can consider:

$$\mathbb{Q}_t |_{\mathcal{F}_s} = \mathbb{Q}_s \text{ for } t \geq s.$$

Hence, we can construct the measure from  $\mathbb{Q}_t$  for a  $t \geq 0$  in to  $\mathbb{Q}$ , as desired.  $\square$

(b) Show that:

$$\mathbb{P}\left(\lim_{t \rightarrow \infty} Y(t) = \infty\right) = 1,$$

while:

$$\mathbb{Q}\left(\lim_{t \rightarrow \infty} Y(t) = \infty\right) = 0.$$

Why does not this contradict the Girsanov theorem?

**Solution.** Recall the **Law of Iterated Log**, we have:

$$\begin{aligned} \limsup_{t \rightarrow \infty} \frac{B_t}{\sqrt{2t \log \log t}} &= 1, \\ \liminf_{t \rightarrow \infty} \frac{B_t}{\sqrt{2t \log \log t}} &= 0. \end{aligned}$$

Now, consider the probability measure of  $\mathbb{P}$ , we have:

$$\lim_{t \rightarrow \infty} \frac{B_t + t}{\sqrt{2t \log \log t}} \leq \lim_{t \rightarrow \infty} \frac{t}{\sqrt{2t \log \log t}} \rightarrow \infty.$$

However, for the probability measure  $\mathbb{Q}$ , we have that:

$$\lim_{t \rightarrow \infty} \frac{B_t}{\sqrt{2t \log \log t}} \text{ not to } \infty \text{ a.s.}$$

Hence, we note that  $\mathbb{P}$  and  $\mathbb{Q}$  does not correspond, this is because  $\mathbb{Q}$  is constructed from  $T \rightarrow \infty$ , but is does not align to the case for concrete  $T$  values.  $\square$

**Problem VIII.7.** (Exercise 8.12 on [Øksendal]). Let:

$$dY(t) = \begin{pmatrix} 0 \\ 1 \end{pmatrix} dt + \begin{pmatrix} 1 & 3 \\ -1 & -2 \end{pmatrix} \begin{pmatrix} dB_1(t) \\ dB_2(t) \end{pmatrix}, \quad t \leq T.$$

Find a probability measure

$Q$  on  $\mathcal{F}_T^{(2)}$  such that  $Q \sim P$  and such that:

$$\tilde{B}(t) := \begin{pmatrix} -3t \\ t \end{pmatrix} + \begin{pmatrix} B_1(t) \\ B_2(t) \end{pmatrix}$$

is Brownian motion with respect to  $Q$  and:

$$dY(t) = \begin{pmatrix} 1 & 3 \\ -1 & -2 \end{pmatrix} \begin{pmatrix} d\tilde{B}_1(t) \\ d\tilde{B}_2(t) \end{pmatrix}.$$

**Solution.** Here, we think about:

$$\tilde{B}(t) = \begin{pmatrix} a(t) + B_1(t) \\ b(t) + B_2(t) \end{pmatrix},$$

so that we have:

$$\begin{pmatrix} 1 & 3 \\ -1 & -2 \end{pmatrix} \begin{pmatrix} a(t) \\ b(t) \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix},$$

and hence  $b = 1$  and  $a = -3$ .

Then, we will think about **Girsanov theorem I**, so we have:

$$M_t = \exp \left( - \int_0^t \begin{pmatrix} -3 \\ 1 \end{pmatrix} \begin{pmatrix} dB_1(s) \\ dB_2(s) \end{pmatrix} - \frac{1}{2} \int_0^t \begin{pmatrix} -3 \\ 1 \end{pmatrix} \begin{pmatrix} -3 & 1 \end{pmatrix} ds \right) = \exp(3B_1(t) - B_2(t) - 5t),$$

which leads to the change in probability measure as:

$$dQ(\omega) = \boxed{\exp(3B_1(T)(\omega) - B_2(T)(\omega) - 5T) dP(\omega)}.$$

□

**Problem VIII.8.** Let  $(\Omega, \mathcal{F}, P)$  be a complete probability space and  $B = \{B_t\}_{t \geq 0}$  be a Brownian motion with respect to filtration  $\{F_t\}_{t \geq 0}$ .

(a) Let  $b : \mathbb{R} \rightarrow \mathbb{R}$  be a bounded continuously differentiable function and  $x$  a fixed real number. Determine a new probability  $Q$  in  $(\Omega, \mathcal{F})$ , the process  $W_t = B_t - \int_0^t b(B_s + x) ds$  is a Brownian motion when  $0 \leq t \leq T$ . Find the SDE  $Y_t = x + B_t$  satisfied with respect to  $Q$ , i.e., with respect to  $W_t$ .

**Solution.** Here, we write the expression in terms of differential form:

$$dW_t = dB_t - b(B_t + x) dt.$$

Then, we use the **Girsanov theorem I** to obtain that:

$$M_t = \exp \left( - \int_0^t -b(B_s + x) dB_s - \frac{1}{2} \int_0^t b^2(B_s + x) ds \right).$$

Hence, with the change in measure, we have:

$$d\mathbb{Q}(\omega) = \exp \left( \int_0^T b(B_s + x) dB_s - \frac{1}{2} \int_0^T b^2(B_s + x) ds \right) d\mathbb{P}(\omega).$$

Then, for  $Y_t = x + B_t$ , we have:

$$dY_t = dB_t = dW_t + b(B_t + x)dt = \boxed{b(Y_t)dt + dW_t}.$$

↓

(b) Let  $F$  be an antiderivative of  $b$ . Prove that  $d\mathbb{Q} = Z_T d\mathbb{P}$  with:

$$Z_t = \exp \left( F(B_t + x) - F(x) - \frac{1}{2} \int_0^t [b'(B_s + x) + b^2(B_s + x)] ds \right).$$

*Proof.* Note that from (a), we have:

$$\begin{aligned} Z_T &= \exp \left( \int_0^T b(B_s + x) dB_s - \frac{1}{2} \int_0^T b^2(B_s + x) ds \right) \\ &= \exp \left( F(B_T + x) - F(x) - \int_0^T \frac{1}{2} b'(B_s + x) ds - \frac{1}{2} \int_0^T b^2(B_s + x) ds \right) \\ &= \exp \left( F(B_t + x) - F(x) - \frac{1}{2} \int_0^t [b'(B_s + x) + b^2(B_s + x)] ds \right), \end{aligned}$$

as desired. □

(c) Let  $Y$  be the solution of:

$$\begin{cases} dY_t = \tanh(Y_t)dt + dW_t, \\ Y_0 = x. \end{cases}$$

Find  $\mathbb{E}[e^{\theta Y_t}]$  the Laplace transform of  $Y_t$  with respect to  $\mathbb{P}$ .

**Solution.** Here, we immediately notice that this is a great model to define another Brownian motion, namely:

$$\tilde{M}_T = \exp \left( - \int_0^T \tanh(Y_s) dW_s - \frac{1}{2} \int_0^T \tanh^2(Y_s) ds \right).$$

Hence, we have  $Y_t$  as a Brownian motion with measure:

$$\begin{aligned} d\mathbb{T} &= \exp \left( - \int_0^T \tanh(Y_s) dW_s - \frac{1}{2} \int_0^T \tanh^2(Y_s) ds \right) d\mathbb{Q} \\ &= \exp \left( - \int_0^T \tanh(Y_s) dW_s - \frac{1}{2} \int_0^T \tanh^2(Y_s) ds + \int_0^T b(B_s + x) dB_s - \frac{1}{2} \int_0^T b^2(B_s + x) ds \right) d\mathbb{P}. \end{aligned}$$

Then, we have the Laplace transformation as:

$$\mathbb{E}_{\mathbb{T}}[\exp(\theta Y_t)] = \exp \left( \frac{1}{2} \theta^2 t \right),$$

and hence, by the change of variable, we have:

$$\begin{aligned}
 & \mathbb{E}_{\mathbb{P}}[\exp(\theta Y_t)] \\
 &= \exp\left(\frac{1}{2}\theta^2 t - \int_0^T \tanh(Y_s) dW_s - \frac{1}{2} \int_0^T \tanh^2(Y_s) ds + \int_0^T b(B_s + x) dB_s - \frac{1}{2} \int_0^T b^2(B_s + x) ds\right) \\
 &= \boxed{\exp\left(\frac{1}{2}\theta^2 t - \int_0^T \tanh(Y_s) dB_s - \frac{1}{2}\theta^2 t - \int_0^T \tanh(Y_s) b(B_t + x) dt\right.} \\
 & \quad \left. - \frac{1}{2} \int_0^T \tanh^2(Y_s) ds + \int_0^T b(B_s + x) dB_s - \frac{1}{2} \int_0^T b^2(B_s + x) ds\right)}.
 \end{aligned}$$

□